RBR
USER GUIDE

RBR*duraturo*^{4}

rbr-global.com

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1 Ruskin software

Ruskin is the only tool you need to manage all your RBR instruments and measurement data. It is available for Mac® and Windows® PC (Ruskin Desktop), as well as for iOS® and Android™ (Ruskin Mobile).

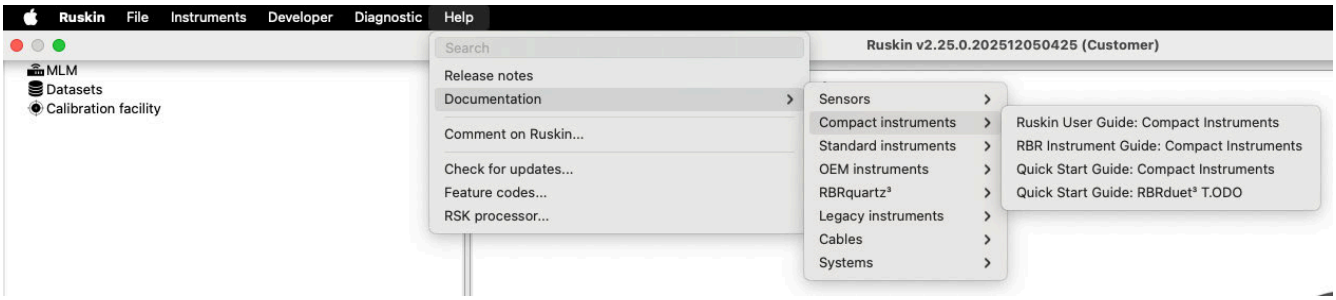
Use the Ruskin software to do the following:

- Configure, schedule, and enable multiple instruments
- Estimate your deployment times
- Download your data after logging
- View your datasets graphically
- Export your data in various formats
- Analyse your data
- Change the calibration coefficients for your instrument
- Perform user calibration
- Contact RBR

RSK files generated by Ruskin contain raw measurement data, firmware and software versions, dates and times, sampling settings, power settings, measured and derived parameters, errors and events, other diagnostic information. They can be read directly in Matlab, or exported to Excel, OceanDataView®, or text files.

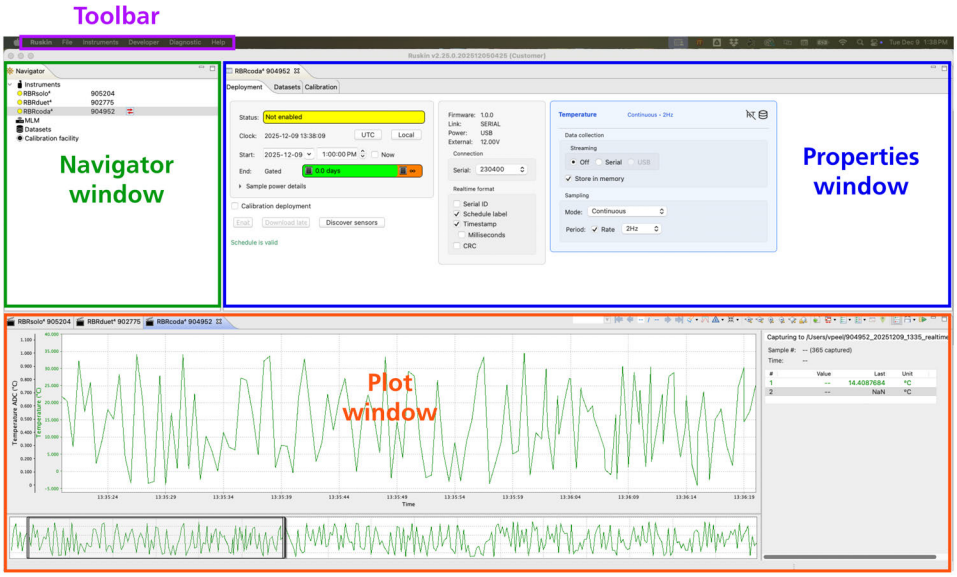
Find Ruskin software for Mac and PC on the USB stick included with your instrument, or visit the RBR website to download the latest version.

The most recent software updates, release notes, Ruskin user guides, instrument guides, and quick start guides are available from the **Help** menu in Ruskin.



2 Ruskin interface

Ruskin software has a user-friendly interface which consists of a **Toolbar** and three main windows: **Navigator**, **Properties**, and **Plot.**



In the **Navigator** window, you will find the list of instruments connected to Ruskin, as well as MLM and winches (if applicable), and dataset files.

When an instrument on the list is selected, the **Properties** window displays three tabs with information related to this instrument: Deployment, **Datasets**, and Calibration. Use these tabs to configure your deployment, check the calibration certificates, and verify your parameters.

The data plot will appear in the **Plot window** below if the realtime option is available and selected for this instrument, or if you click the **Poll** button on the far right of the toolbar.

Click-and-drag window tabs to rearrange the windows within Ruskin, or move a window outside of Ruskin. Hover over a side of a window, and when the cursor becomes a two-way arrow, move it to adjust the window size.

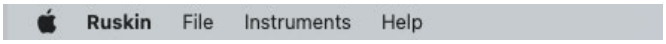
Click the **Close** button in the top right corner to close a window. For example, you can close the **Navigator** window to have a better view of the **Properties**. The closed window icon will appear on the sidebar (in this case, **Navigator**). Click the **Multiple windows** button above the closed window icon to re-open it.

Double-click a window tab to maximise that window, and double-click the tab again to return it to the original size.

Alternatively, use the **Single window** and **Multiple windows** buttons.

When you restart Ruskin, it returns to its original layout.

The **Toolbar** at the top left above the **Navigator** window has four dropdown menus. If you are using a Mac computer, it appears as follows:

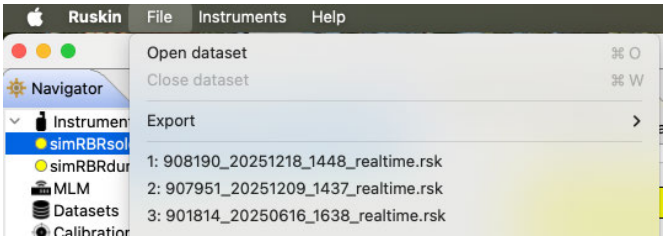


On a Windows PC, the **Toolbar** looks slightly differently:

The rest of the interface is the same between the two systems.

2.1 File

Go to the **File** dropdown menu to open or close a dataset, export your data, and see the list of available datasets. The **Datasets** menu in the **Navigator** windows duplicates some of these options for convenience.

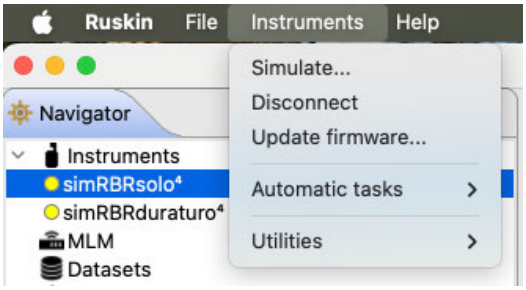


2.2 Instruments

Go to the **Instruments** dropdown menu to Simulate an instrument, Update firmware, set up Automatic tasks, or access the **Utilities**.

Automatic tasks and **Utilities** are not applicable for sensors.

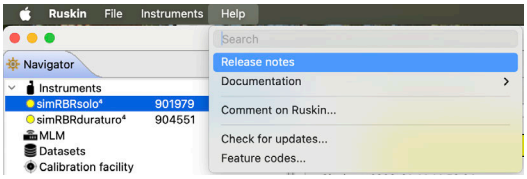
The **Utilities** option is a support tool. Contact RBR before using it.



You can also access the **Simulate…** and **Automatic tasks** options by selecting the **Instruments** context menu in the Navigator window.

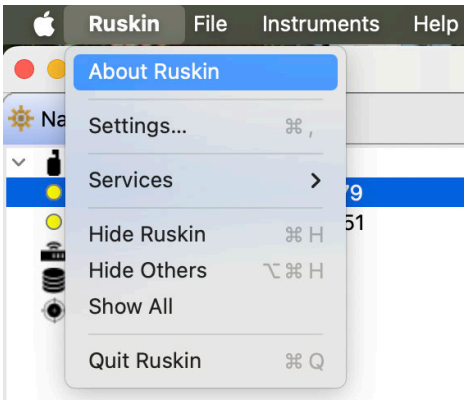
2.3 Help

Go to the **Help** dropdown menu to access the latest Release notes and Documentation, **Comment on Ruskin…**, Check for updates**…**, as well as access Feature codes. On Mac, you can also use the **Search** option.

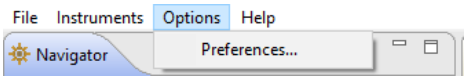


2.4 Ruskin / Options

On your Mac, go to the **Ruskin** dropdown menu to access information on your current software version, edit your Settings, or **Quit Ruskin**. Note that the rest of the options on this dropdown menu depend on your operating system and are external to Ruskin.



On your Windows PC, edit you Settings using **Options** > **Preferences**.



3 Installation

Ruskin is the only piece of software you need to operate your RBR instruments. RBR releases Ruskin software versions compatible with Mac and PC (Ruskin Desktop), as well as with iOS® and Android™ (Ruskin Mobile).

Install the Ruskin Mobile app on your mobile device by going to the Apple App store or Google Play.

Follow the steps below to install Ruskin Desktop on your computer.

3.1 Install Ruskin on PC

You can install Ruskin on a PC that runs the Windows 7, 8, 10, or 11 operating system.

The minimum requirements for Ruskin are:

- OS = Windows 7
- Processor speed = 1.4GHz
- RAM required = 8GB
- Display resolution = 1024x768
    - 1920x1080 (recommended)
- HDD space for installation = 2GB

The instruments use either a USB interface or an RS-232 serial port to communication with Ruskin.

Steps

⚠ Realtime sensors will not require USB drivers to operate, they are only required for our standard and compact instruments.

1. Connect the USB stick included with your instrument to a port on your computer.
2. Navigate to the **Ruskin Installation** folder and double click on the on the file `RuskinSetup.exe`.
3. Follow the installation wizard. By default, Ruskin will be installed to `C: \RBR`
4. At the end of the installation, you will see a prompt asking, “Would you like to install the logger driver at this time?”
5. Click **Yes** to install the drivers

⚠ You may need to run the setup application as an administrator to install the driver correctly.

A shortcut to Ruskin will appear on the desktop and in a **Start** menu folder.

ℹ The most recent version of Ruskin software can be found at https://rbr-global.com/products/software.

3.2 Install Ruskin on Mac

You can install Ruskin on a Mac running OS X 10.12 (Sierra) or later.

⚠ Always use the default **Applications** folder as the working directory.

Steps

1. Connect the USB stick included with your instrument to a port on your adaptor.
2. Navigate to the "OSX" folder and double-click on the file `Ruskin.dmg`.
3. When the disk image window opens, drag the Ruskin icon into the **Applications** directory and wait for the copy to complete. An application named "Ruskin" will appear in the **Applications** folder.
4. Right-click on the icon, and select **Open**.
5. The dialogue box shown below will prompt you to authorise the opening of Ruskin.

⚠ You may need to navigate to **System Settings...** > **Privacy & Security** > **Allow applications from** and select **App Store & Known Developers** to complete the installation.

3.3 Update Ruskin

To take advantage of new features and bug fixes, ensure that you are using the most recent version of Ruskin.

- Find the most recent version of Ruskin at https://rbr-global.com/products/software.
- Receive an automatic notification about a new release when you start the application.
- Check from within Ruskin by navigating to **Help** > **Check for updates...**.
- Send an email to support@rbr-global.com, subject: "Ruskin update request", and ask us to add you to the mailing list. You will receive an email as soon as the new version is released.

If you have a broadband connection, simply follow the installation instructions on your computer. Otherwise, request a USB stick from RBR.

⚠ It is not necessary to uninstall the older version of Ruskin before installing the newer version. The installation program deletes the older files before installing the newer ones. It does not delete any Ruskin data files or log files.

3.4 Uninstall Ruskin

Uninstall Ruskin only if you no longer need to manage RBR instruments from your computer.

It is not necessary to uninstall the older version of Ruskin before installing the newer version. The installation program deletes the older files before installing the newer ones. For more information, see Update Ruskin.

> ⚠ Removing Ruskin will not delete your data files or your diagnostic logs, provided they have not been saved to the Ruskin installation folder.

Uninstall Ruskin on a PC, Windows 7, 8, 8.1, 10, or 11

1. Go to **Start** > **Control Panel** > **Programs**.
2. Under **Programs and Features**, click **Uninstall a program**.
3. Find **Ruskin** on the list.
4. Click **Ruskin** to highlight it.
5. Click **Uninstall**.

Uninstall Ruskin on a Mac, OS X 10.12 or later

Move the Ruskin application from **Applications** to the **Trash**.

4 Support

⚠ When experiencing an issue, look for a solution under the **Help** menu before contacting RBR.

You can get in touch with RBR in several different ways:

- Send us an email. For technical questions, use support@rbr-global.com, and for general inquiries, info@rbr-global.com.
- Contact us via the website at https://rbr-global.com/contact-us/.
- Call us at +1 (613) 599-8900.
- Send us a bug report from within Ruskin itself **Help** > **Comment on Ruskin**

The **Help** menu in Ruskin offers access to technical documentation, feedback forms, and software updates. On Mac, you can also search for Ruskin menu options.

4.1 Release notes

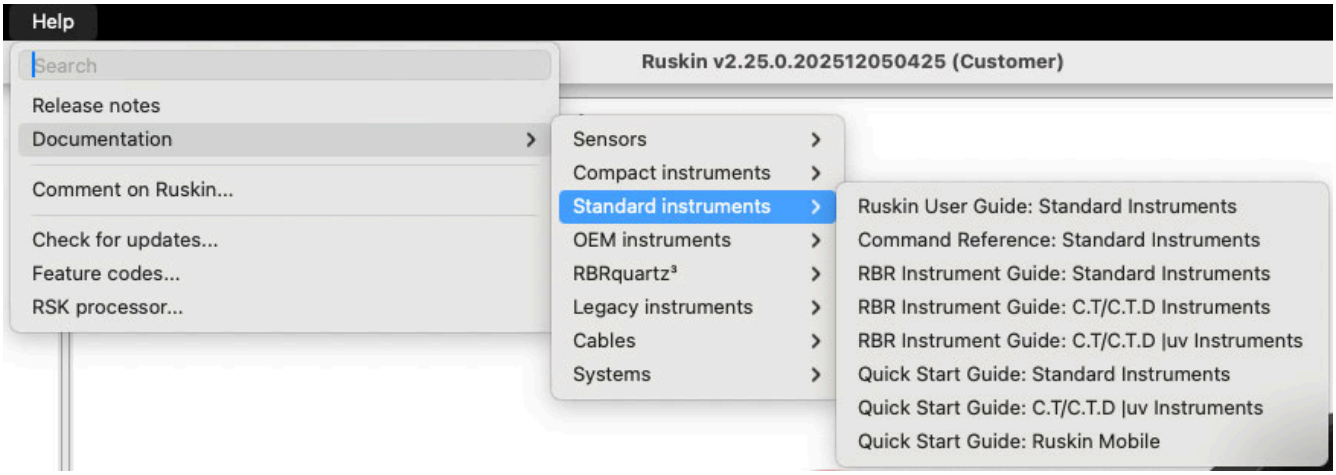
Go to **Help** > **Release notes** to open the **Welcome** window. It will outline new features, improvements, and bug fixes associated with each release version.

Select **Click here to see all Release notes** to see the full history of the release notes. The link will take you to the RBR support page. Alternatively, scroll down to see brief recaps of the release notes from all previous versions.

To exit and return to the **Navigator** mode select **x** on the **Release notes** tab

4.2 Documentation

Select **Help > Documentation** to access an instruments Quick Start Guide, Instrument Guide, and Command reference.



Documentation can also be found on the RBR website.

4.3 Comment on Ruskin

Sending a bug report from within Ruskin allows you to include the diagnostic logs, RSK datasets, screenshots, and any other files that could help us reproduce the problem and find the solution as quickly as possible.

To submit a bug report:

1. Click on **Help** > **Comment on Ruskin...** . The **Feedback to RBR** form will appear.
2. Enter your **Name** and **Email address**.
3. Enter a brief **Summary** of the problem.
4. Provide a detailed **Description** (serial number for the instrument, overview of the problem, deployment details, initial tests, and, for software bugs, steps to reproduce the issue)
5. Include any attachments, if required.
6. Verify all the information entered and select **Submit**.

4.4 Check for updates

To search for the latest software version, go to **Help** > **Check for updates**.

If your software is up-to-date, no further action will be required.

If an update is found, Ruskin will offer to install it. Follow the prompts then restart Ruskin for the updates to take effect.

4.5 Feature codes

Sometimes, RBR may release new features to certain users only, as a beta trial. This includes:

- Features in early development
- Features supporting a new product, in preparation for the product launch
- Features requested by a specific customer

Usually, the goal is to get feedback and improve the feature before its official release. Contact your sales representative or RBR support team at support@rbr-global.com if you have questions about your feature code.

To access a new feature:

1. Click on **Help** > **Feature codes...**, to access the **Feature codes** window.
2. Enter the feature code provided by RBR.
3. Click **ADD**.

If the code is correct, Ruskin will save the feature in the local database and enable it. In most cases, you will have access to the new feature immediately, without restarting Ruskin. If addition instructions are required, you will receive them along with the feature code.

Errors

- The feature code is not valid.
    - This error may indicate the code was entered incorrectly or it is not compatible with the current version of Ruskin.
- The feature code is already enabled.
    - This error may occur when another user has already activated this code.

5 Quick start - Ruskin Desktop

Ruskin Desktop version is designed for computers and laptops. It generates dataset files which include raw measurement data, firmware and software versions, dates and times, sampling settings, power settings, measured and derived parameters, errors and events, calibration coefficients, and diagnostic information, offering the fullest Ruskin experience.

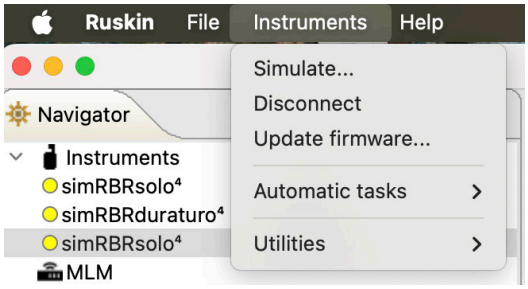
5.1 Simulate an instrument

Ruskin can simulate most instruments and sensors that RBR produces. We recommend that you experiment with different simulated options before enabling a schedule for your actual deployment. This practice will also help you become more familiar with how an RBR instrument interacts with Ruskin and how to configure its settings and features. Work with simulated instruments the same way as you work with a real RBR instrument, configuring, calibrating, and fetching data.

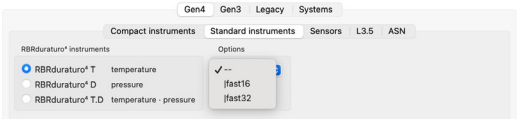
⚠ Currently, you cannot enable simulated instruments or download their data. For more information, see Deploy your instrument.

Steps

1. From the **Instruments** menu, click **Simulate**…



The **Configure simulated instrument** dialog box will appear.



2. Click your instrument family and make your selections.
3. Click OK to proceed.

ℹ Depending on the instrument selected, the **Options** dropdown menu may contain | fast sampling rates, | tide and | wave variants, tilt, or no options at all (in that case, the menu will be greyed out).

4. Your instrument will appear under **Instruments** in the **Navigator** windown. Simulated instruments will have the prefix “sim” in front of their name.

The instrument properties will be displayed on the right, under three tabs:

- Deployment - displays status, clock, sampling mode and speed, power options, and deployment estimates based on these parameters.
- Datasets - displays the datasets contained in the instrument. Provides functionality to download and delete individual datasets.
- Calibration - allows access to the current calibrations for each channel in the instrument.

Familiarise yourself with the instrument by changing configuration options and comparing deployment estimates. Select the desired configuration using the dropdown options or entering the values manually in the fields provided.

For simulated instruments, the **Plot** window will remain empty unless you click the **Poll** button  .

Manage multiple instruments by switching between them in the **Navigator** window.

To remove a simulated instrument from Ruskin, right-click the instrument name in the **Navigator** window, and select **Disconnect**. You can also use the **Instruments** menu.

Alternatively, simply close its **Plot** tab by clicking the **X.** The instrument will disappear from the list.

5.2 Deploy your instrument

Before using your RBR instruments, you may want to experiment with different options by simulating your instrument on Ruskin.

When you are ready to use your physical RBR instrument, follow the steps below to ensure that you measure exactly what you want on the first attempt.

Steps

- Locate a USB-C port inside of the instrument. See the section on opening and closing your instrument in the relevant Instrument Guide for more details. Guides are available on Ruskin under **Help** > Documentation.
- Plug one end of the USB cable (USB-C to USB-C, provided with your instrument) into this port and the other, in the USB port on your computer.
  The instrument will appear in the **Navigator** view after a few seconds. The properties for the instrument will be displayed in the **Properties** window, grouped under three tabs: Deployment, **Datasets**, and Calibration.
- If you are using the instrument for the first time, you can use either the default preferences or specify your own. For more information, see **Settings > General**. You can change them at any time.
- Click the instrument you want to use. Verify that it contains the expected sensors under the Calibration tab.
- Click the Calibration tab to view or modify calibration coefficients.
- Click the **Deployment** tab and go to the Scheduling cards section to select the mode and speed of measurements.

Ruskin will allow a deployment to run until the instrument can no longer sample. This could be due to a full memory or due to power supplies being exhausted. It will display the estimated battery usage and storage capacity based on the parameters you enter. The green widget next to **End** will indicate the number of days your instrument would be sampling, along with the icon representing the limiting factor, battery or memory.

Carefully consider this information before you enable a deployment schedule. For more information, see Schedule.

- Click the **Enable** button at the bottom of the **Deployment** tab to take samples according to the schedule that you specified.

Your deployment will continue until the battery runs out, the memory is full, or you stop your schedule manually.

- When your deployment stops, click the **Download latest** button at the bottom of the **Deployment** tab to transfer all the sampled data from the instrument to your computer. For more information, see Download latest. As soon as you download a new dataset, it will appear in the **Navigator** window. Refer to Dataset files for details on managing and analysing your data.

If you want your data streamed or fetched, specify these preferences before you enable the schedule:

1. To see live data sampled every few seconds, click the **Poll** button

   on the far right of the toolbar above the **Plot** view, without enabling the schedule.
2. To start streaming, click **Enable**. The data will immediately appear in the **Plot** window below. The instrument does not store streamed or fetched samples, but Ruskin will record them in the realtime RSK file.

To restore a closed connection to an instrument on Ruskin, click **Instruments** in the **Navigator** window. A list of all instruments physically connected to your computer will appear in the **Properties** window.

Find your instrument and deselect its checkbox, and then select it again.

Your instrument will re-appear in the **Navigator** window.

5.3 Recover your instrument and download data

When deployment is complete, recover your instrument and follow these steps to download your data.

Flooded instruments may be under pressure and opening them may be dangerous. Take precautions when opening an instrument after deployment.

Steps

1. Start Ruskin.
2. Carefully remove the battery end-cap. See "Opening and closing the instrument" section in the corresponding RBR Instrument Guides for more details. The Guides are available on Ruskin under **Help** > Documentation.
3. Locate a USB-C port inside of the instrument.
4. Plug one end of the USB cable (USB-C to USB-C, provided with your instrument) into this port and the other, in the USB port on your computer.
5. The instrument will appear in the **Navigator** view after a few seconds.
6. Under the **Datasets** tab, click **Download**. See Download latest for details.
7. The file is automatically downloaded to the location specified in **Settings** > **General**. See General on steps to set up your default location.
8. Evaluate your data. See Analysis for details.

Disconnect from your instrument

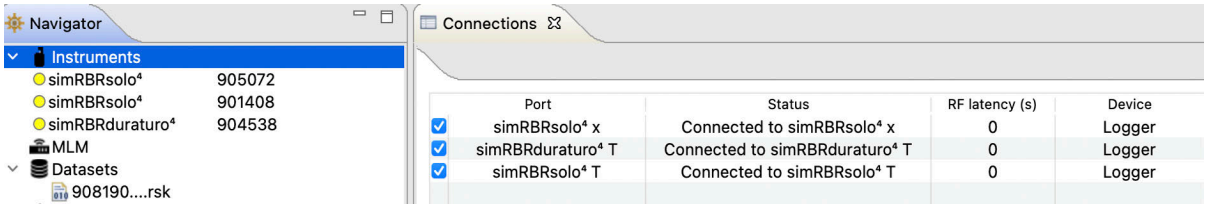
To disconnect an instrument from Ruskin, right-click it in the **Navigator** window, and select **Disconnect**. You can also use the **Instruments** menu.

Alternatively, simply close its **Plot** tab by clicking the **X.** The instrument will disappear from the list. Please note that you will be able to reconnect to it at any time because Ruskin remembers the port of a plugged instrument.

Reconnect to your instrument

To restore a closed connection to an instrument on Ruskin, click **Instruments** in the **Navigator** window. A list of all instruments physically connected to your computer will appear in the **Properties** window, under the Connections tab.

Find your instrument and deselect its checkbox, then reselect it again. Your instrument will re-appear in the **Navigator** window.

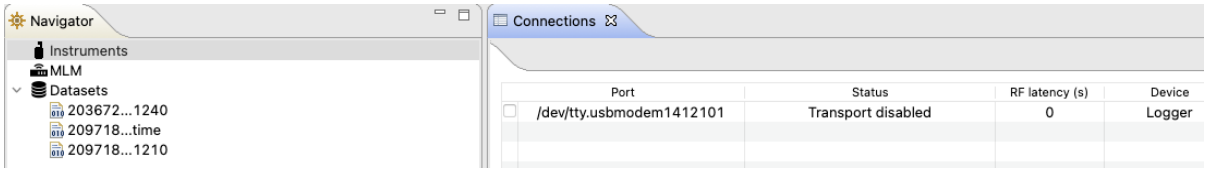


Remove your instrument

To completely remove your instrument from Ruskin, unplug it from your computer.

Alternatively, deselect the checkbox next to your instrument, and Ruskin will disable transport to its port.

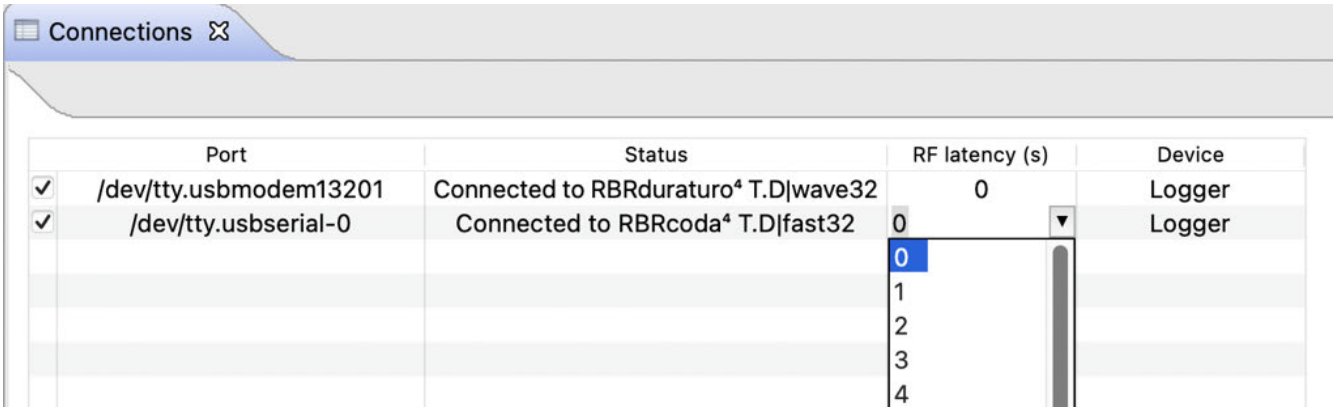
> ⚠ If you uncheck this port, Ruskin will never detect the instrument again on that port. To use this port for an instrument, the port must be checked/enabled.



6 Connections

Use the **Connections** tab to view and manage devices connected to your computer via physical ports or Ethernet.

In the **Navigator** window, click **Instruments.** The **Connections** tab will open on the right. The table will include ports, statuses, RF latency selections, and the device type for each connected device.

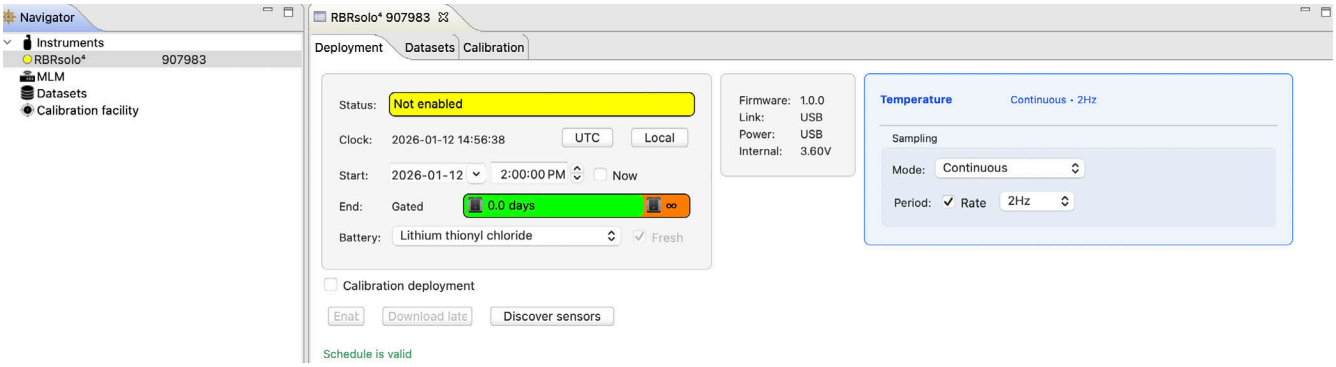


Column	Information
Port	If your instrument is plugged in to your computer, this column will identify the physical port by name, such as "**COM5**" (if using Windows) or by its address, such as "**/dev/tty.usbmodem141101**" (if using MAC OS).
Status	The column will display a success message, such as "**Connected to RBRconcerto³ 209681**", or an error message, such as "**Unable to connect to host**".
RF latency (s)	From the dropdown menu, select a value up to **29** seconds. The selected value will extend the allowable time for an instrument to respond to a command. Use this option when on a long cable or slow Wi-Fi connections.
Device	The column will display the device type for each connected device: • **Logger**: Instruments connected via USB, serial (RS-232), or TCP connections • **RS-485**: Instruments connected via serial (RS-485) connections • **GPS**: NMEA streaming devices

See **Deploy your instrument** on how to locate the USB-C port on your instrument and connect it to your computer.

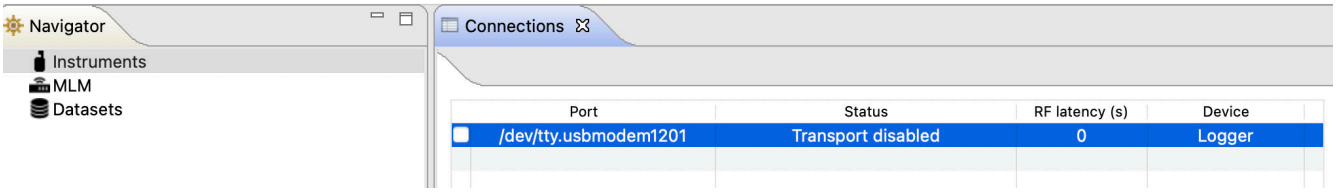
As soon as you plug in an instrument, Ruskin will detect it and add it to the list.

Click on one of the instruments to switch to its Deployment tab.



If you unplug an instrument, the port will remain enabled as long as the port checkbox remains selected. Ruskin will automatically reconnect to the instrument when it is plugged back in.

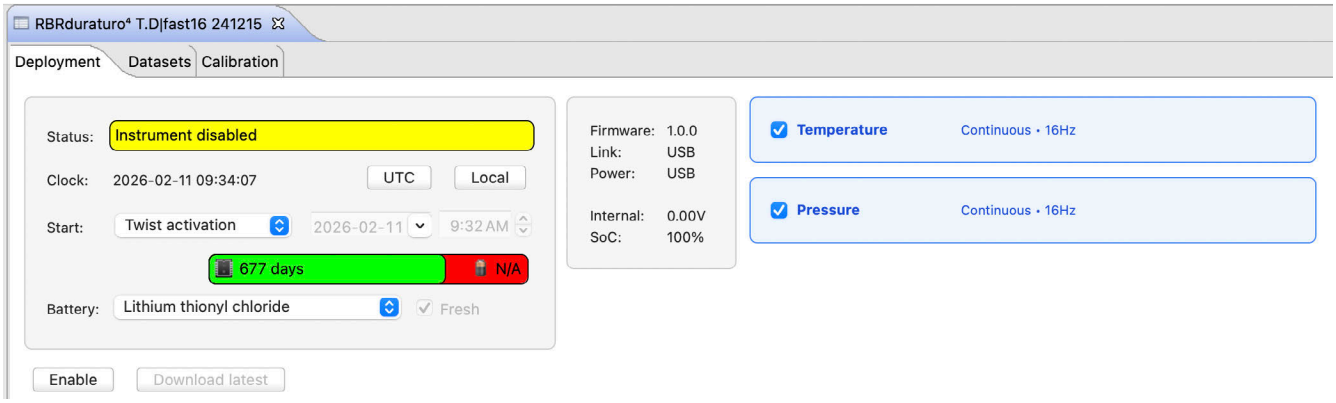
Deselect the checkbox next to your instrument to disable transport to its port. After this, Ruskin will not detect any instrument plugged into this port.



To restore transport, reselect the checkbox. Your instrument will re-appear in the **Navigator** window.

7 Deployment

Use the **Deployment** tab to set up your deployment parameters.



After setting up a desired schedule, click **Enable.** New values will replace all previously stored deployment and schedule parameters.

> The instrument must be disabled to change a setting. A new deployment must be enabled for the new settings to take effect.

You can also use the **Deployment** tab to view general information for each of your instruments, such as serial number, firmware version, power type (internal or external), and voltage.

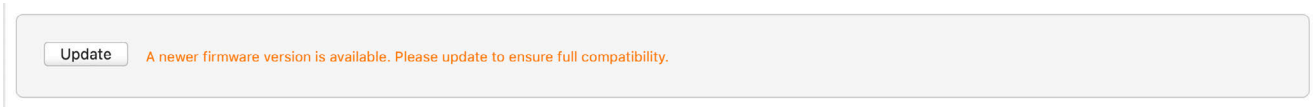
The SoC (State of Charge) value indicated for the internal source indicates the power remaining in your batteries.

> It is not a good idea to use voltage as a health indicator of the battery as the voltage drop in certain chemistries can be very sharp.

7.1 Update firmware

Ruskin automatically checks if your instrument firmware is up-to-date. Updates may be critical, routine, or customised.

If a newer version is available and this update is critical, the **Update firmware** button and a warning message will appear at the top of the **Deployment** tab.

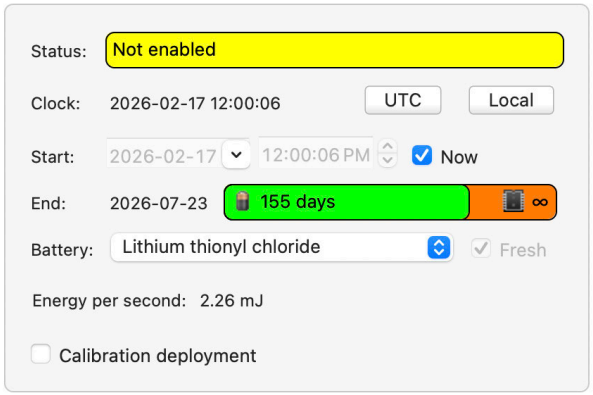


See Critical firmware updates for details.

7.2 Schedule

The **Schedule** section includes four fields: **Status**, **Clock**, **Start**, and **End**.

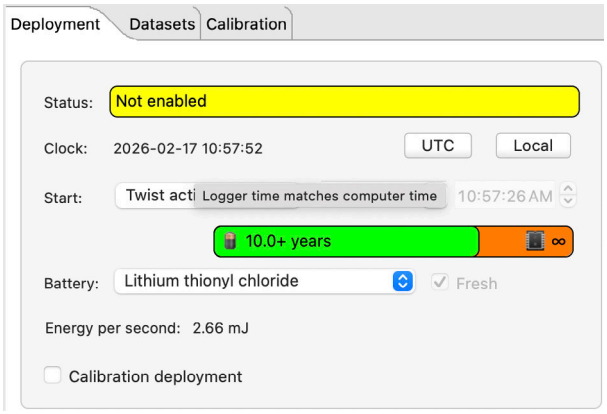
The **Status** field displays the current state of your instrument.



Status	Description
Not enabled	A deployment has not been enabled.
Configuring instrument	Ruskin is writing the deployment configuration to the instrument.
Schedule enabled	A deployment has been enabled, but the start time has not yet been reached.
Paused	A deployment has been enabled, but a gating condition has not been met.
Logging in progress	A deployment has been enabled and the instrument is currently obtaining samples and recording them to memory.
Logging, memory full	A deployment has been enabled and the instrument is currently obtaining samples, but they are not being recorded to memory as there is no available space. Data continues to be transmitted over the chosen realtime link.
Stopped, schedule complete	A deployment has reached the end time and so has been stopped.
Stopped, memory full	The memory has been completely filled with samples and so logging has been stopped.
Stopped, user request	An enabled deployment has been stoped by user intervention.
Failed	An internal error has occurred during a deployment.
Battery failed	An internal error with regarding the batteries has occurred.

Clock

The instrument clock may drift up to 60s per year. Hover your mouse over the time value to display the offset.



Synchronise the instrument clock before each deployment. Select **UTC** or **Local** time, depending on your preferences.

Start

The **Start** date and time are only editable If the **Start** condition is set to **Scheduled.** Otherwise, it is the **Start** condition selection that will control the start of logging. See Gating for details.

End

The **End** date is calculated by Ruskin autonomy engine and indicates when your deployment is likely to stop. This is based on sampling schedule, mode, and power selections . Ruskin autonomy engine provides feedback on which parameter (power or memory) will be exhausted first.

The parameter in the **green** bar is the true deployment estimate. In the example shown, your deployment will last 155 days, until the battery is exhausted.

Ruskin uses power tracking data stored in the instrument to adjust its autonomy calculation to account for power already used from previous deployments. If new batteries are inserted in the instrument, check the 'fresh' check box next to the battery selection. This will indicate that the autonomy calculation should assume fresh batteries for the deployment.

The parameter in the **orange** bar indicates that your instrument could last longer than the number of days indicated in the green if the preceding parameter were not a factor.

If the **End** logging date is power dependent and if you know that the instrument will be operating under very cold conditions, you may want to lower the demands on the battery by lengthening your sampling period or opting for different battery chemistry.

Ruskin autonomy engine

Ruskin autonomy engine relies on several parameters to estimate the deployment end date: sampling rate, power options, and memory. One of the key factors is battery life.

Battery life prediction is a complicated issue. In RBR instruments, it is a strong function of the type of instrument, type and number of sensors attached, sampling mode (sampling rate, gating conditions, realtime data collection), and water

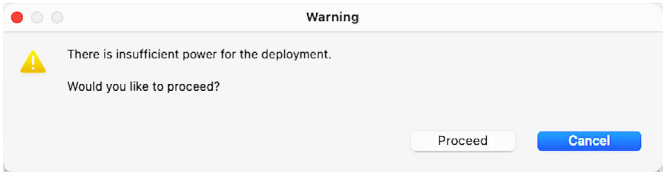
temperature during the deployment. Manufacturer data for the batteries may not reflect the way batteries are used in RBR instruments, and thus, are not always informative.

Autonomy figures depend on the power draw of the instrument, as well as the derated capacity of the battery pack. Batteries are derated to 4°C. These values differ for different battery chemistries. For the most accurate deployment estimates, select the same batteries from the dropdown menu as installed in your instrument.

Ruskin calculates the expected battery usage for the instrument during setup . The nominal capacity of each type of battery is described in the Power section and is given in mAh at room temperature. Battery voltage does not decrease linearly and is therefore not an accurate indicator of battery capacity.

RBR tested batteries of various brands at 6°C; all of them were able to provide the threshold capacity defined in the Power section. View these predictions and further de-rate the batteries if the expected deployment is in cold water.

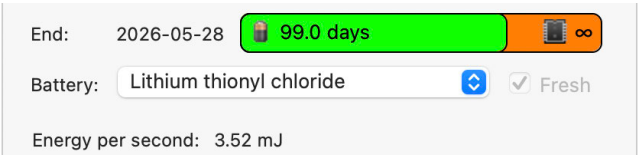
The software will warn you if the expected battery usage for a particular deployment scenario is approaching the theoretical potential mAh.



The software will not prevent your instrument from being started even if a warning is given. However, adjusting deployment parameters or replacing the batteries may help extend deployment times.

7.3 Power

The **Power** section includes battery chemistry options. Ruskin autonomy engine uses these parameters to estimate deployment life.



The **Battery** dropdown menu shows available chemistry options for internal batteries. The list depends on your instrument.

RBR ships all new instruments with batteries of the highest capacity for the instrument type already installed.

Mixing batteries of different chemistries, brands, and age will reduce performance and potentially damage the instrument. Improperly matched batteries may become overheated, leak, or even explode.

Typically, RBR instruments are shipped with EVE ER14505 lithium thionyl chloride or Energizer L91AA lithium iron. Select your battery chemistry from the dropdown list.

Name	Chemistry	Voltage (V)	J*
Lithium thionyl chloride	Li-SOCL $_2$	3.6	209,950
Alkaline	Zn-MnO_2	1.5	64,800J
Nickel metal hydride	Ni-MH	1.2	36,720

*The nominal capacity of each type of battery is given at room temperature.

Deployment estimates

Ruskin estimates autonomy figures based on the power draw of the instrument, as well as the derated capacity of the batteries. Batteries are derated to 4°C . These values differ for different chemistries (see above). For the most accurate deployment estimates, select the same batteries from the dropdown menu as installed in your instrument. Alternatively, use Ruskin to simulate your instrument with different batteries and find which chemistry works best for your deployment.

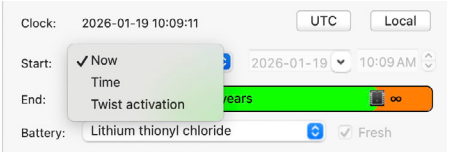
Battery cells of the same chemistry but from different manufacturers may have different performance. If the nominal capacity of the battery model you are using is lower than outlined above, your actual deployment may be shorter than the estimate.

Replace batteries before each deployment to maximise the operational time and prevent data loss.

Select the **Fresh** checkbox when installing fresh batteries in your instrument for the next deployment. When checked, Ruskin autonomy engine will reset usage statistics and adjust deployment estimates accordingly.

7.4 Gating

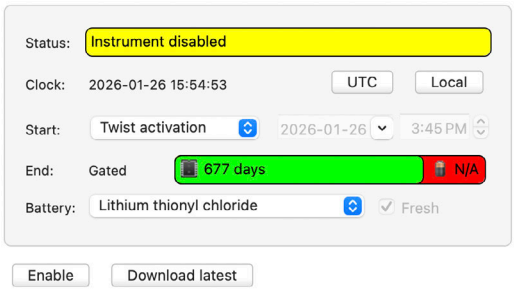
Gating allows you to enable your deployment using a method other than time-based. From the dropdown menu next to **Start**, select **Now** to start your deployment straight away, **Time** to **Schedule** your deployment at the date and time selected in the fields to the right, or **Twist activation** to start your deployment by twisting the end-cap.



Twist activation

When you select **Twist activation**, the instrument starts to sample based on the twist on/off position of its end-cap rather than a schedule.

To start sampling, first click **Enable**. This button is at the bottom of the **Deployment** tab.



The button will then become a **Stop** button. The status will become "Deployment paused".

Turn the battery end-cap to the **RUN** position.
The instrument will vibrate with one long pulse and start sampling.

To pause it, turn the battery end-cap to the **PAUSE** position. The instrument will vibrate with three short pulses to indicate it has stopped logging.

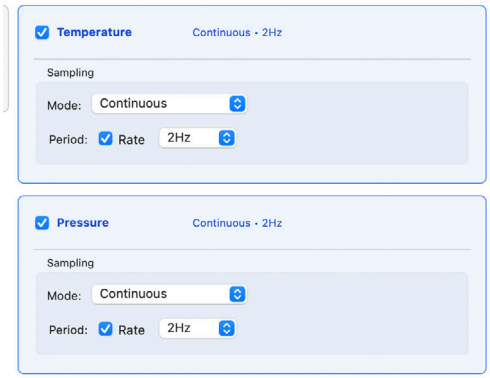
⚠ Twisting the end-cap to the **RUN** or **PAUSE** position will activate the Wi-Fi. However, twisting to **PAUSE** will also pause the instrument. Twisting to **RUN** will resume sampling.

7.5 Scheduling cards

The Scheduling cards represent the sensors on the instrument, so each sensor will have a separate card allowing each sensor to be scheduled independently.

Each card includes a **Mode** field, as well as several optional fields available with certain sampling modes. If the fields are not visible click anywhere on the card to expand it.

To schedule a sensor ensure the checkbox next to the sensor name is selected.



When connecting an RBR*solo*^{4} x or RBR*duet*^{4} D.x, Ruskin select **Discover sensors** to request Ruskin to search for the correct sensor.

Mode

Depending on your instrument, different dropdown options may be available. See Average, Burst, Directional, Tide, and Wave for information on how to configure these modes.

Speed and Rate

These are the only two parameters you need to configure **Continuous** sampling mode.

Check **Period** to select the sampling **Rate** in Hz from the dropdown menu. The default option is always the highest instrument rating. For example, | fast32 will default to 32Hz.

> All profiling instruments (known as | fast) can sample faster than 2Hz and support Average and Burst modes. All | tide and | wave instruments can average at rates of 2, 4, 8, 16 or 32Hz.

Uncheck **Period** to enter the sampling **Rate** manually in hours, minutes, and seconds (HH:mm:ss format). The fastest rate to enter manually is 1s. Type the numbers in, or use the up and down arrows.

7.5.1 Average

When set to **Average**, the instrument will collect data at a certain rate, and then average those samples to produce a single value to store on the instrument. This sampling mode allows you to save memory during long deployments.

In addition to **Rate,** there are two more parameters required for **Average** mode: **Measurement duration** and **Period**.

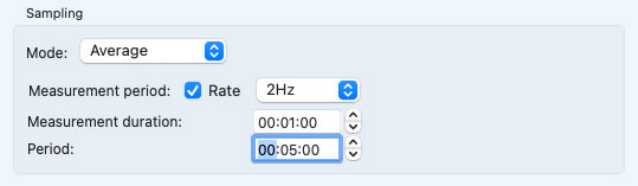
Measurement duration specifies the time range over which to average. It must always be longer than **Rate**.

Period is the repetition period for performing the averaging. It must always be longer than **Measurement duration**.

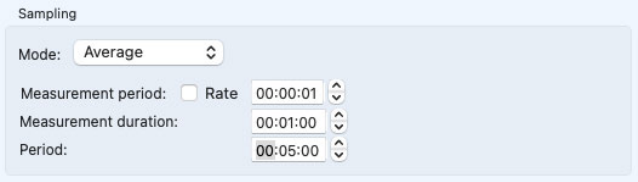
Sampling controls

When using the advanced version, select two or all three parameters manually.

In the example shown, the sampling rate selected is 2Hz (two samples per second). The instrument will be logging for a duration of one minute, then pause and average the 120 samples collected. After an interval of five minutes, it will start logging again, repeating the same cycle.



In the second example, the sampling rate selected is 1s (1Hz, or one sample per second). **Measurement duration** and **Period** are the same in both examples.



At every **Period**, the instrument records only one sample, averaged over all samples collected during the period of **Measurement duration**. The rest of the samples are discarded after averaging is performed.

7.5.2 Burst

When set to **Burst**, the instrument will collect a specified number of samples at a specified rate, and repeat this operation at a specified interval.

Only instruments with the | fast sampling feature support **Burst** sampling mode.

In addition to **Rate,** there are two more parameters required for **Burst** mode: **Measurement count** and **Period**.

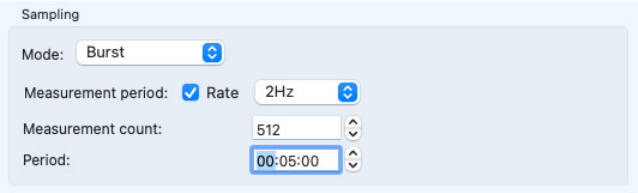
Measurement count specifies the number of samples to record.

Period is the repetition period for performing the burst. The countdown begins at the same moment the burst starts and, therefore, **Period** must always be longer than the time it takes to obtain the number of samples indicated in **Measurement count**.

Sampling controls

Select **Rate**, **Measurement count**, and **Period** from pre-defined options in three dropdown menus.

In the example shown, the sampling rate selected is 2Hz (two samples per second). The instrument will be logging for a duration of 512 samples (256 seconds), then pause for 44 seconds (that is, until the countdown reaches 300s or five minutes). After an interval of five minutes, a new burst of 512 samples will occur, the instrument repeating the same cycle.



7.5.3 Tide

Tide sampling mode collects data at a certain rate, and then averages those samples to produce a single value to store on the instrument. When set to **Tide**, the instrument uses averaging to remove wave noise data from pressure measurements.

All instruments with the | tide32 and | wave32 features support **Tide** sampling mode.

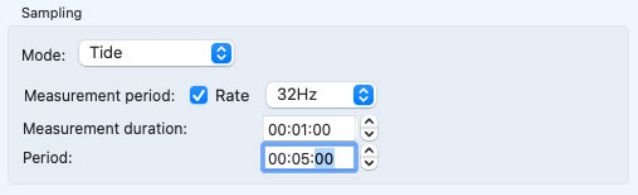
In addition to **Rate,** there are two more parameters required for **Tide** mode: **Measurement duration** and **Period**.

Measurement duration specifies the time range over which to average. It must always be longer than **Rate**.

Period is the repetition period for performing the averaging. It must always be longer than **Measurement duration**.

Sampling controls

Select **Rate** from pre-defined options in the dropdown menu. Then manually enter the **Measurement duration** and **Period**



In the example shown, the sampling rate selected is 32Hz (32 samples per second). The instrument will be logging for a duration of one second, then pause and average the sixteen samples collected. After an interval of five minutes, it will start logging again, repeating the same cycle.

At every **Period**, the instrument records only one sample, averaged over all samples collected during the period of **Measurement duration**. The rest of the samples are discarded after averaging is performed.

7.5.4 Wave

Wave sampling mode collects a specified number of samples at a specified rate, and repeats this operation at a specified interval. When in **Wave** mode, the instrument takes multiple pressure readings in a burst and reconstructs the surface wave time series. This mode records both tide and wave information.

Only instruments with the | wave32 feature support **Wave** sampling mode.

Measurement period or **Rate** are parameters defining individual pressure readings.

- The highest possible frequency visible in the data is limited to ½ the sampling rate. However, this mathematical limit cannot be achieved because of wave attenuation, and real data are actually lower.
- The sampling rate defines the resolution of the frequency spectrum which can be calculated from the wave data.
- The sampling rate, together with the burst duration, defines the lowest frequency which can be assessed in a wave burst.

In addition to **Measurement period** and **Rate,** there are two more parameters required for **Wave** mode: **Measurement Duration** and **Period.**

Measurement duration specifies the number of samples to record.

Period is the repetition period for performing the burst. It must always be longer than the time it takes to obtain the number of samples indicated in **Measurement duration**.

Consider unique aspects of deployment environment when setting up **Wave** sampling mode.

For example, while a 30-minute interval tends to work in most cases, shorter intervals may suit better when encountering ocean swells which have longer wavelengths than noise but shorter than tide.

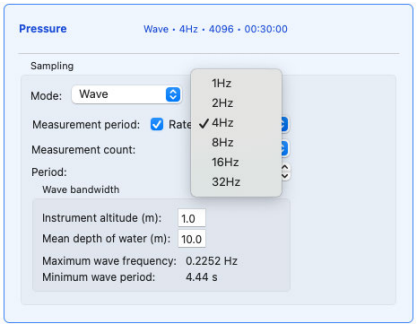
Furthermore, you may enter **Instrument altitude** and **Mean depth of water** to estimate possible wave periods for your deployment. These parameters are not mandatory for the instrument to work, but allow you to get an idea of what to expect.

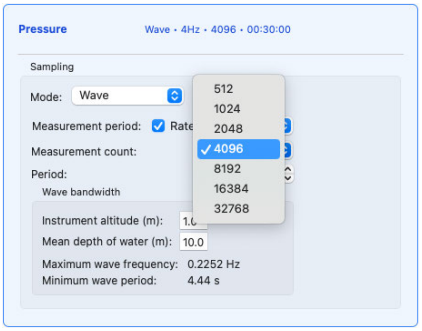
- **Instrument altitude** is the actual height of the instrument in metres above the seabed. This is defined by deployment requirements, and the instrument must be physically affixed at this height during the installation.
    - This parameter is stored on the instrument and used to compute wave statistics for pre-deployment analysis.

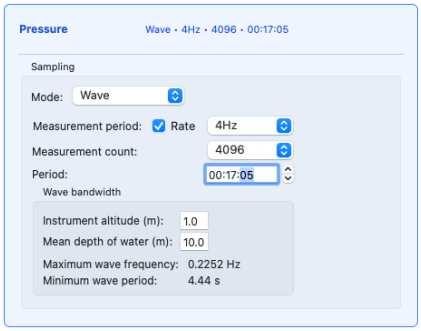
- **Mean depth of water** is an estimate of the average water depth in metres, used for the initial prediction of wave frequency. It must always be greater than **Instrument altitude.**
    - This parameter is not stored in the logger and only used to compute wave statistics. It is adjusted post-deployment through the RSK file.
    - Ruskin will calculate the actual mean depth of water from the instrument altitude and its depth measured during the deployment.

Sampling controls

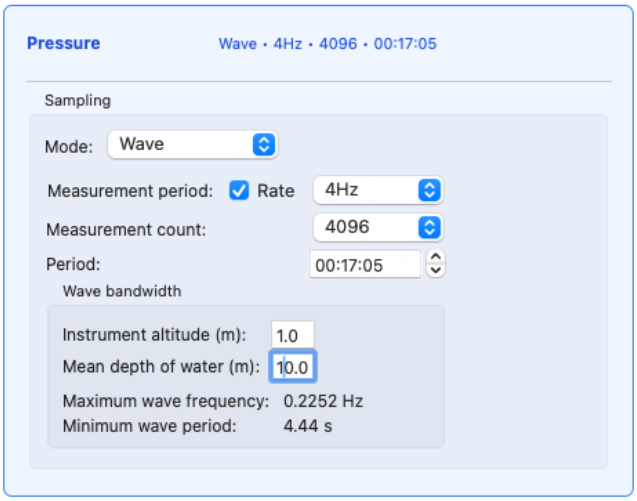
Select **Rate** and **Measurement count** from the drop-down menus, and enter **Period** manually. For example, with a rate of 4Hz and a duration of 4096 samples, the instrument will be sampling 17 minutes 4 seconds. You can set up near continuous sampling by setting the interval to 17:05. Logging will be on every second except the one remaining second of the interval, and then start again.







Enter **Instrument altitude** and **Mean depth of water** manually. Estimates for wave statistics will be immediately displayed: maximum wave frequency and minimum wave period (essentially, they reflect the same concept because period = 1/frequency). These values can be adjusted post-deployment through the RSK file.



The timestamp of the burst for both **Tide** and **Wave** datasets is the beginning of the burst.

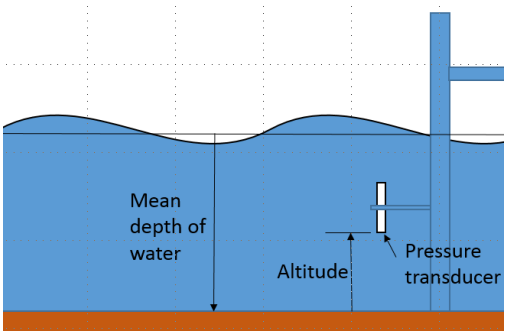
Deployment depth of | wave32 instruments

The basic rule is to place the instrument as close to the surface as possible without it emerging from the water due to large waves or low tides.

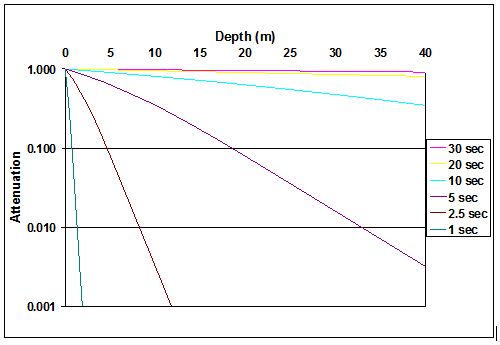
Attach your | wave32 instrument to a suitable support below the surface of the water, such as a dock or other rigid mooring, to completely immobilise it.

Enter the expected mean depth of water and the known instrument altitude (height above the seabed). From these values, Ruskin will estimate wave frequencies and wave periods that your instrument could measure (period = 1/frequency). On data retrieval, Ruskin will calculate the actual mean depth of water from the instrument altitude entered and its depth measured using the pressure transducer, and then use this actual depth for computing all wave statistics during deployment.

The physics of what a pressure transducer can measure depends on the height of water above as well as the depth of water below it. High frequencies attenuate very quickly with depth. The depth of the deployment is critical in determining frequencies/periods of the wave data the instrument will be able to capture. It is the depth, not orientation of the pressure transducer that affects these measurements.



Instrument fixed to a dock below the water surface



Wave attenuation as a function of depth for various wave periods

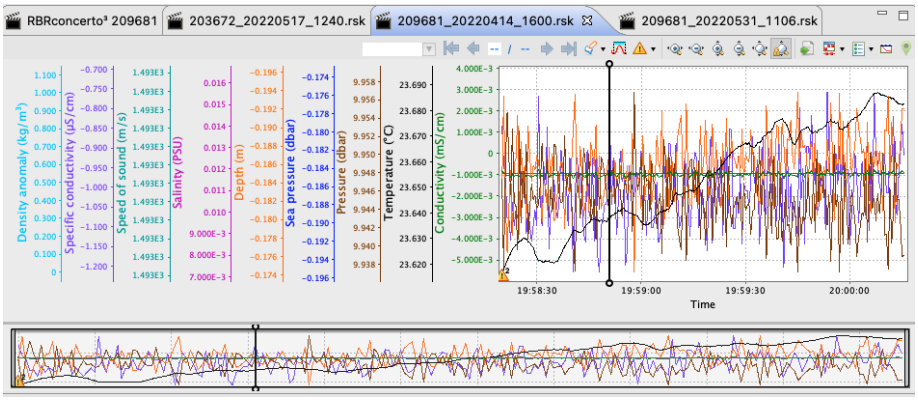
7.6 Download latest

There is a button on the **Deployment** tab labelled **Download latest**. This button downloads the latest dataset stored in the instrument. This dataset could be still recording.

> ⚠ RBR recommends storing your data on a local drive ratherthan a network storage drive. Cloud storage options such as GoogleDrive and Dropbox may extend download times.

Steps

1. Click **Download latest**. The file is automatically downloaded to the location specified in **Settings** > **General**, and names it as it appears in the **Datasets** tab.
2. The new dataset will appear automatically in **Navigator** window under **Datasets**.
3. The **Properties** window will change to the dataset view, with the following tabs: **Overview**, **Analysis**, and **Channels**.
4. All the data stored on the instrument at the time of the download will be automatically plotted in the **Plot** window.

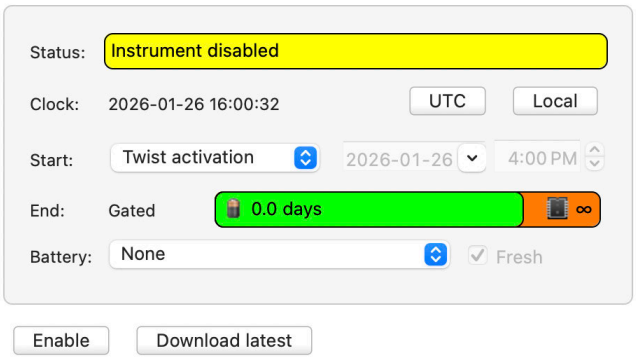


When you download data again while on the same schedule, the RSK file will append it with any new data stored since the last download. This default behaviour can be changed in **Ruskin** > **Settings** > **General** > **Download options**.

7.7 Enable / Stop

Ensure that your instrument is ready to be deployed before enabling a schedule. See Deploy your instrument**.**

To allow the instrument to start logging, click **Enable**. This button is at the bottom left of the **Deployment** tab.



The **Enable** button will now read **Stop**. The status will become "Deployment paused", "Deployment gated", or "Sampling in progress", depending on the configuration.

Logging will start when one of the following occurs:

- The **Now** button is checked
- The **Start** time arrives
- The battery end-cap is turned to the run position, starting the **Twist activation**

If the maximum number of deployments have been recorded, you will not be able to click **Enable**.

Before proceeding, download the data from your instrument (see **Download**).

> ⚠ All editable fields become greyed out after you enable a schedule.
>
> To change any deployment parameters, stop your instrument, adjust the settings, and start a new deployment.

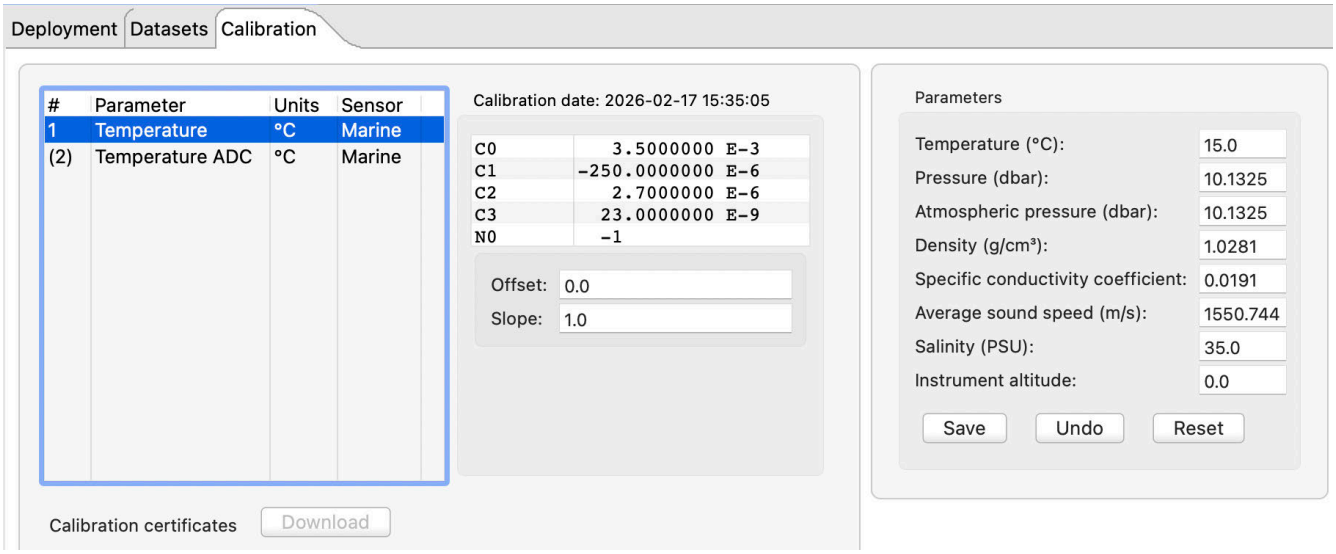
To manually stop the instrument, click **Stop.**

Logging will stop on its own when one of the following occurs:

- The **End** logging time is reached
- The battery end-cap is turned to the pause position
- The power source is removed or depleted
- The memory is filled

8 Calibration

Under the **Calibration** tab you can confirm measured and derived parameters for your instrument. It also displays calibration coefficients for each parameter, the date and time of the last calibration, and all the parameters the RBR instrument may need for calculating derived channels. Select a sensor from the table to display its calibrations.



If you see a warning sign on the **Calibration** tab, this indicates that the calibration is out of date and needs to be recalibrated.

RBR calibration certificates contain calibration equations, coefficients, and residuals for each sensor.

The date of the latest calibration is always displayed. A warning sign will appear on the tab when your calibration certificate is out of date.

RBR recommends calibrating your instrument before any critical deployment, periodically once a year, or if you suspect the readings to be out of specifications.

Discuss your calibration requirements with RBR. In some cases, the instrument may need to be returned to RBR to have it checked and recalibrated.

To contact RBR for our current calibration fees, click **Request calibration quote** and complete the **Request for quote** form.

Calibration controls

You can edit the calibration coefficients, displayed as "C" values: C0, C1, C2, C3. As soon as you make a change and move to another cell, a new calibration date will be displayed. Also, **Save** and **Undo** buttons will become active.

Use **Save** to save the new values.

⚠ Always click **Save** to save new coefficients on the instrument. Otherwise, all changes will be lost once your session is closed.

Use **Undo** to recover to the original coefficients if you have not already saved your changes to the instrument.

⚠ You cannot use **Undo** after clicking **Save**. Once the coefficients are saved to the instrument, you will need to restore old values manually and save them again.

Parameters

The **Parameters** table displays all the parameters the RBR instrument may need for calculating derived channels.

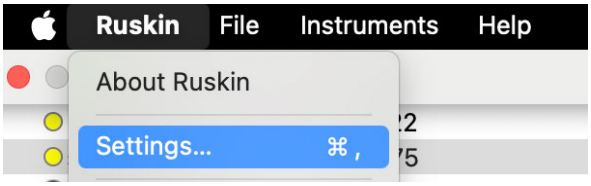
If your instrument can measure a parameter, it will use the measured value. Otherwise, you can enter the necessary values manually, and they will take effect immediately.

For example, you always need atmospheric pressure and water density for derivation of depth. Default values in Ruskin correspond to sea level and sea water. Therefore, it is especially important to adjust these parameters when working at high altitudes in fresh water.

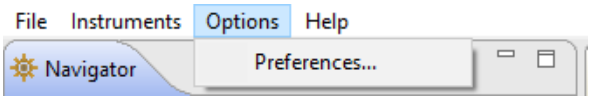
Enter atmospheric pressure (in dbar) and water density (in g/cm^3) manually in the table under the **Calibration** tab. If not entered, default values of 10.1325dbar and 1.0281g/cm^3 will be used.

9 Settings

On your Mac, access **Settings** from the **Ruskin** dropdown menu in the top toolbar.



On your Windows PC, use the **Options** dropdown menu to set up your preferences.



Factory-set global defaults require no changes in most situations. However, as you learn more about what Ruskin can do, you may want to change some of these settings to better suit your requirements. The global preferences include:

- Derived channels (applies to some legacy instruments)
- Facility (authorised users only, requires login)
- General (download locations and options, sampling and calibration controls, export options)
- Plotting (channel visibility and channel colours)

9.1 Derived channels

> ⚠ The **Derived channels** settings are intended for XR(X),1060, 2050, and 1050 RBR legacy data loggers. They do not apply to newer generations. They do not apply to any RBR*coda* or RBR*coda*^{3} instruments.
>
> Newer generations calculate all possible derived channels for that specific instrument.
>
> Use the Calibration tab in the instrument **Properties** window to set up initial parameters for calculating derived channels. For downloaded files, use the Parameters tab in the dataset **Properties** window.

The **Derived Channels** section of the **Preferences** dialog box has four tabs: **Depth**, **Conductivity - Salinity**, **Dissolved O2**, and **No sensor values**, where you can choose additional channels derived from measured channels.

Derived channels calculated by the instrument as well as those calculated by Ruskin are automatically added to the default channel list in both the live **Plot** view and the static dataset.

Depth

If your instrument has a pressure channel, you can use its measurements to derive a depth channel. The data calculated for this derived channel appear along with measured channels in the **Plot** view and in datasets.

1. Select the **Enable Depth Channel** checkbox.

   > ⚠ For newer generation instruments, all derived channels are calculated regardless of the checkbox status.

2. In the **Atmospheric Pressure** box, type the value in dbar or use the default value. This value corrects the pressure measurements during the depth calculation.

> ⚠ The default **Atmospheric Pressure** value is 10.1325. Adjust this value manually to represent a different altitude.

3. Select either the **Simplified calculation** or **Seawater calculation**.

> ⚠ Ruskin can calculate depth based on the simplified calculation or the UNESCO seawater calculation. The instrument always calculates depth using the simplified calculation.

   a. To use the simplified calculation, type the actual water density, or use the default value. Note that for freshwater, the density should be set to 1.0.

   b. To use the UNESCO seawater calculation, specify the latitude of the data collection in degrees and minutes.

Conductivity - Salinity

If your instrument has a conductivity channel, you can use its measurements to derive salinity, density anomaly, specific conductivity, and speed of sound.

1. Select the **Use conductivity correction for derivation** checkbox.

> ⚠ For newer generation instruments, all derived channels are calculated regardless of the checkbox status.

2. In the **Hydrostatic pressure** box, type the value in dbar or use the default value.
3. Select derived channels to include in your calculations.
4. For the speed of sound, select between UNESCO, Del Grosso, and Wilson equations.

Dissolved O2

You can derive a dissolved oxygen channel that measures oxygen saturation as a percentage.

1. Click the **Dissolved O_2** tab and select the **Enable Dissolved Oxygen Channel** checkbox.

> ⚠ For newer generation instruments, all derived channels are calculated regardless of the checkbox status.

2. If your instruments use the Oxyguard DO or RINKO DO sensor, select the **Derive concentration using the Weiss equation** checkbox and the output unit: µMol/L, mg/L, or mL/L.

> ⚠ The Weiss equation requires values for temperature and salinity. If your instrument does not measure them, you can specify standard values on the **No sensor values** tab.

3. If your instruments use the Aanderaa Optode DO sensor to measure oxygen saturation, select the **Derive concentration using the Weiss equation** checkbox and the output unit: mg/L or mL/L.
4. If any of your instruments use the Aanderaa Optode DO sensor to measure oxygen concentration, select the **Calculate saturation using the Garcia and Gordon equation** checkbox.

> ⚠ The Garcia and Gordon equation requires values for temperature and salinity. If your instrument does not measure them, you can specify standard values on the **No sensor values** tab.

No sensor values

Enter salinity, pressure, and temperature values used to calculate the derived channels when a sensor is not available.

If you suspect that the derived channel value is incorrect, check to make sure that the **No sensor values** entries match the deployment environment.

For example, if a dissolved oxygen saturation measurement is made in a lake at 8°C but the **No sensor values** salinity is 35 and the temperature is 15°C, concentration reported will be incorrect.

Adjust the **No sensor values** entries and recompute.

9.2 General

Use the **General** settings page to set up file locations, language, download options, sampling and calibration controls, and export options.

You can click **Apply** to save your changes without closing the dialogue box.

File location

You can control where RSK files, realtime RSK file, and log files are stored by default.

Specify these locations before downloading any data by typing in a directory name or by browsing.

RSK files are the datasets obtained from your instrument.

Realtime RSK files are generated when a connected instrument is streaming or when you enable fetching mode on the instrument.

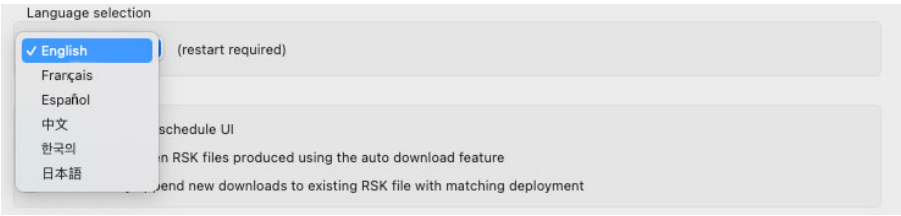
Log files are generated by Ruskin and help when diagnosing issues. These files are automatically attached to issues generated using the **Comment on Ruskin** feature.

RBR recommends storing your datasets on a local drive rather than a network storage drive. Cloud storage options such as GoogleDrive and Dropbox may extend download times.

You can change where future files are stored by default at any time. When done, click **Apply** or **Apply and close**. The changes will take effect immediately.

Language selection

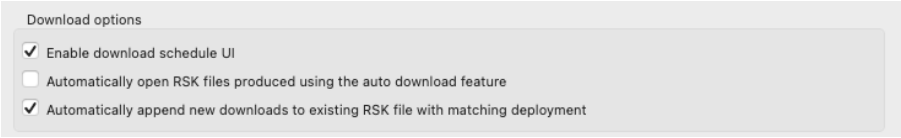
Ruskin is available in six languages: English, French, Spanish, Simplified Chinese, Korean, and Japanese.



Select your language from the dropdown menu and click **Apply** or **Apply and close**. Ruskin will need to restart for the changes to take effect.

Download options

Select the appropriate checkboxes to change your download preferences.



The **Enable download schedule UI** checkbox is only for legacy instruments.

When done, click **Apply** or **Apply and close**. The changes will take effect immediately.

Export options

Select the checkbox to enable raw data export. Use this option for downloading your RSK file when storage space is limited or expensive. The dataset will be exported in the most compact raw binary format.

When done, click **Apply** or **Apply and close**. The changes will take effect immediately.

9.3 Plotting

Adjust default settings for the graphical display in the **Plot** view. Manage selections in **Channel visibility** and **Channel colours**, and apply them globally.

You can click **Apply** to save your changes without closing the dialogue box.

Channel visibility

The **Channel visibility** tab displays many options to hide or show specific information.

Opt for displaying errors and events for a more informative graph, or hide them for a cleaner view.

Select the **By default, hide all measured channels** checkbox to display only derived channels.

Select the **By default, hide all derived channels** checkbox to display only measured channels.

Otherwise, pick and choose channels to display or hide.

When done, click **Apply** or **Apply and close**. The changes will take effect immediately.

You can override visibility preferences in the **Plot** view for any particular graphical display.

Channel colours

The **Channel colours** tab allows you to choose a different colour for each channel that is shown for information currently running in **Plot** view, or from an opened dataset. Select from the list of pre-defined options or create your own colour.

When done, click **Apply** or **Apply and close**. The changes will take effect immediately.

10 RSK files

The RSK file is a single file database based on SQLite that allows us to have large files with high-speed access to any part of the dataset. RSK files have different types and versions, which reflect historical changes to the underlying dataset structure. To upgrade the version of an older RSK file, go to Overview tab.

RBR provides open-source RSKtools toolboxes for both Matlab (RSKtools) and Python (pyRSKtools) to read, post-process, visualise, and export RSK files.

RSK files can be exported to Excel, OceanDataView®, or text files.

RSK files contain data recorded by the instrument or sensor, firmware and software versions, dates and times, sampling settings, power settings, measured and derived parameters, errors and events, other diagnostic information.

For datasets obtained via streaming or polling, the RSK format is **Realtime**. Their file names contain the "realtime" label.
This file format is available for RBR standard instruments and RBR realtime sensors when in streaming mode, and for all instruments when polling.

> Datasets recorded in **Calibration** storage format allow changes to calibration coefficients. You must explicitly select this option if you wish to manipulate calibration coefficients after the data has been recorded.

> GPS mapping for RSK files relies on manually added location points.

To identify the type of the RSK file, go to the **Overview** tab.

File naming convention for datasets obtained during deployments

By default, RSK file names are composed of the following information:

- The instrument serial number: six digits
- The date of the deployment (YYYY-MM-DD): eight digits
- The time of the deployment (HH-MM in the 24-hour format): four digits

For example, the file named 209681_20260204_1306.rsk contains the dataset for an instrument with a serial number of 209681; the start time of the deployment was February 04, 2026 at 13:06 (01:06pm), local time.

The data recorded from the current and previous deployments are stored in the instrument. They can be accessed (downloaded or deleted) from the Datasets tab. You can also download the latest deployment from the Deployment tab. Download them to your computer before starting a new deployment. Go to **Preferences > General** to change your default location for RSK downloads.

> RBR recommends downloading deployments as soon as possible to ensure data is recorded in a safe location.

File naming convention for realtime datasets

By default, realtime dataset names are composed of the following information:

- The instrument serial number: six digits
- The date of the download (YYYY-MM-DD): eight digits
- The time of file creation (HH-MM in the 24-hour format): four digits
- The "realtime" label, indicating the data were streamed or fetched from the instrument

For example, the file named 209682_20260205_1408_realtime.rsk contains the dataset for a streaming instrument with a serial number of 209682; the data collection started on February 05, 2026 at 14:08 (02:08pm), local time.

The data streamed or polled from your instrument are automatically saved to your computer. Go to **Preferences > General** to change your default location for realtime RSK files.

> ⚠ The file extension is .rsk; it indicates the Ruskin file format and must not be edited. If you change it, your new file extension will become part of the dataset name, and the .rsk extension will be appended.

11 Realtime data format

Real-time data is data that is either automatically streamed from the instrument during a deployment or asynchronously polled from it. Streaming is only available for instruments with an underwater data connection. Polling is available on all units.

When polled data is the only live option on the instrument, the data will have the following format:

```
<Timestamp> <value1> <value2> ... <valueN><CR><LF>
```

Example:

```
2026-02-04 07:55:32 23.3254 10.1149 0.1149 0.1149
```

This is an example of an RBR*duraturo*^{4} T.D polling all channels (temperature_00, pressure_00, seapressure_00, depth_00)

If the instrument supports streaming over an underwater connection, the format of the live data will be identical between both streamed and polled samples. The instrument provides the flexability to change the format of the output for different applicaitons, however, the default format for streamed data set via Ruskin will be the following:

```
<schedule label> <Timestamp> <value1> <value2> ... <valueN><CR><LF>
```

The schedule label is important to differentiate the schedule from which the data came when deploying an instrument with multiple schedules.

Example:

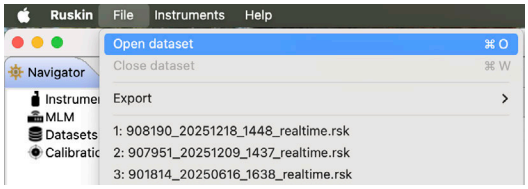
```
sch_Pressure 2026-02-04 08:00:00 10.1149 0.1149 0.1149
sch_Temperature 2026-02-04 08:00:00 23.3254
```

In this example, the RBR*duraturo*^{4} T.D has been deployed with two schedules and both are set to stream. The Temperature channels are on one schedule and the Pressure channels are on another. The schedule label allows the parser to associate the streamed data with different schedules.

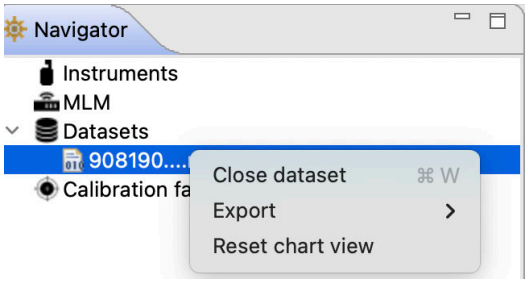
12 Dataset files

Datasets are RSK files generated by Ruskin and have an .rsk extension. After downloading your datasets, you can view and analyse your data using the options below.

Go to the **File** dropdown menu to open or close a dataset, export your data, and see the list of available datasets.



The **Datasets** context menu in the **Navigator** windows duplicates some of these options for convenience.



When a dataset on the list is selected, the **Properties** window displays three tabs with information related to this dataset.

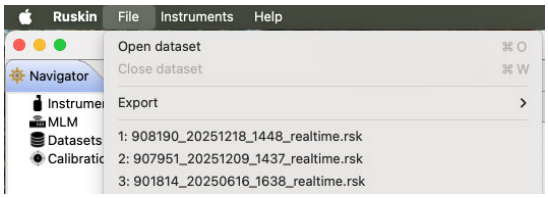
Use these tabs to analyse your data, check the calibration certificates, and verify your parameters.

12.1 Open dataset

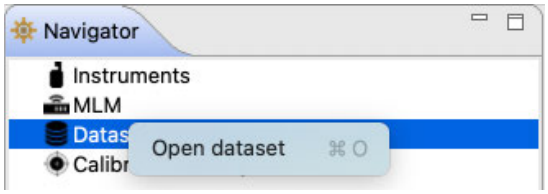
Open any stored dataset from the **File** menu in the top toolbar or from the **Datasets** menu in the **Navigator** view.

Steps

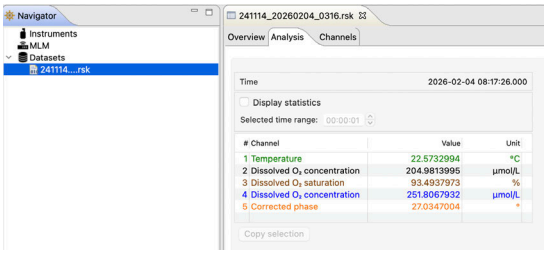
1. Select **File** > **Open dataset**



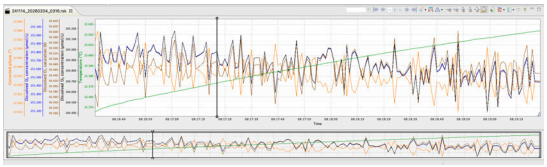
Alternatively, right-click **Datasets** in the **Navigator** view and select **Open dataset.**



2. A browsing window will appear. Double-click the .rsk file you want to view, or select the file and click **Open**.
3. The name of the dataset appears and is highlighted automatically in the **Navigator** view. The **Properties** view changes to the dataset view, with four tabs: **Overview, Analysis**, **Channels**, and **Calibration**. It will open to the **Analysis** tab by default.



4. The data in the file will automatically appear in the **Plot** view.



To close a dataset, go to **File** > **Close dataset**. Alternatively, right-click the dataset name in the **Navigator** view and select **Close dataset**.

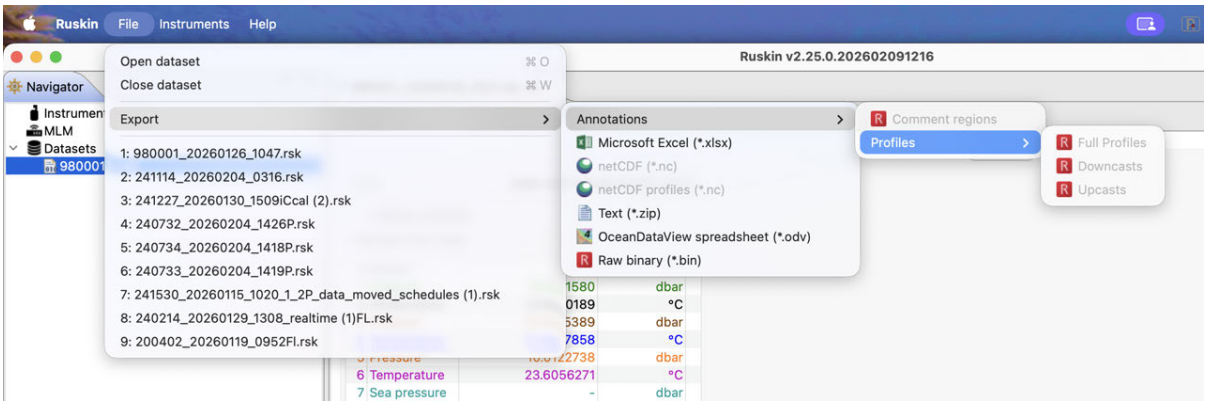
Alternatively, simply close its **Plot** tab by clicking the **X.** The dataset will disappear from the list.

12.2 Export

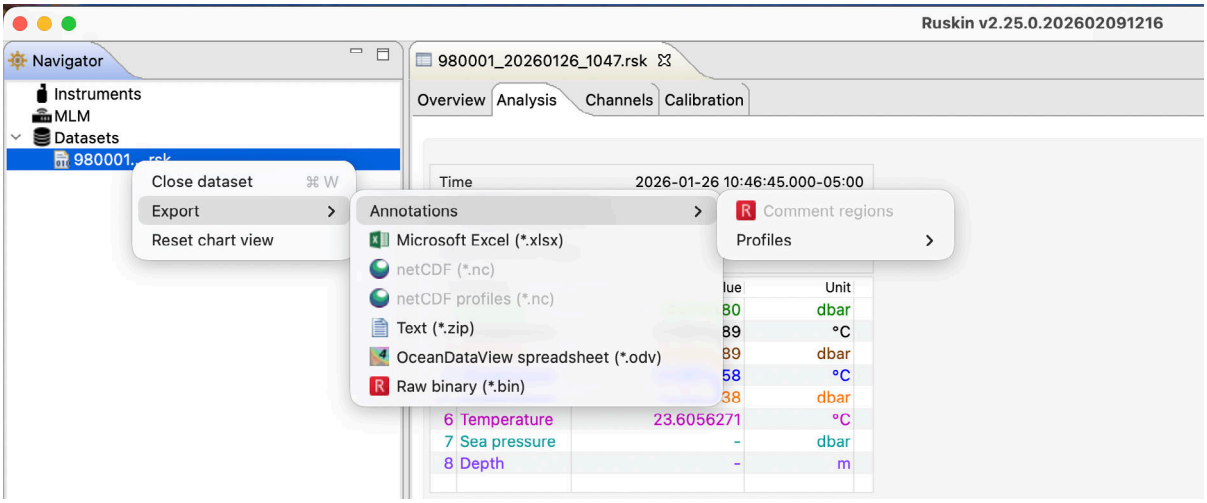
Use the **Export** option to share your data with others or analyse your data using other software. Datasets can be read directly in Matlab with our toolkit RSKtools, or exported to Excel, OceanDataView®, or text files.

Steps

1. **File** menu > **Export**, then hover to open a set of submenus.



or right-click the dataset in the **Navigator** window, then hover to open a set of submenus.



2. Select the appropriate export format (**Microsoft Excel**, **netCDF**/**netCDF profiles**, **Text**, **OceanDataView spreadsheet**, or **Raw binary**).

> For realtime RSK files, the **Raw binary** export format is not available.

3. If exporting annotations, select the category: **Full profiles**, **Downcasts**, or **Upcasts**.
4. Specify a location and a name for the data file.
5. Click **Save**.

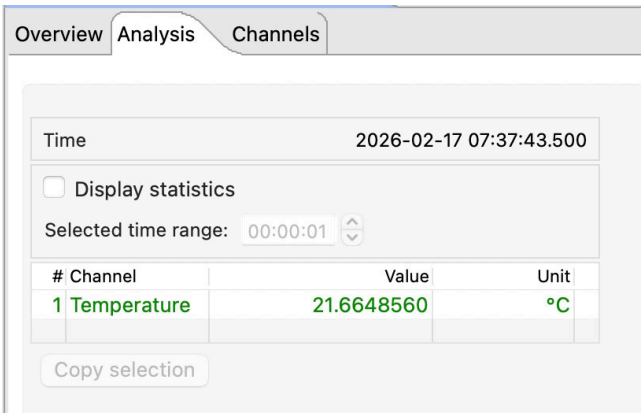
12.3 Analysis

Select a dataset in the **Navigator** view.

The **Properties** view will change to dataset properties, with three tabs: **Overview**, **Analysis**, and **Channels**.

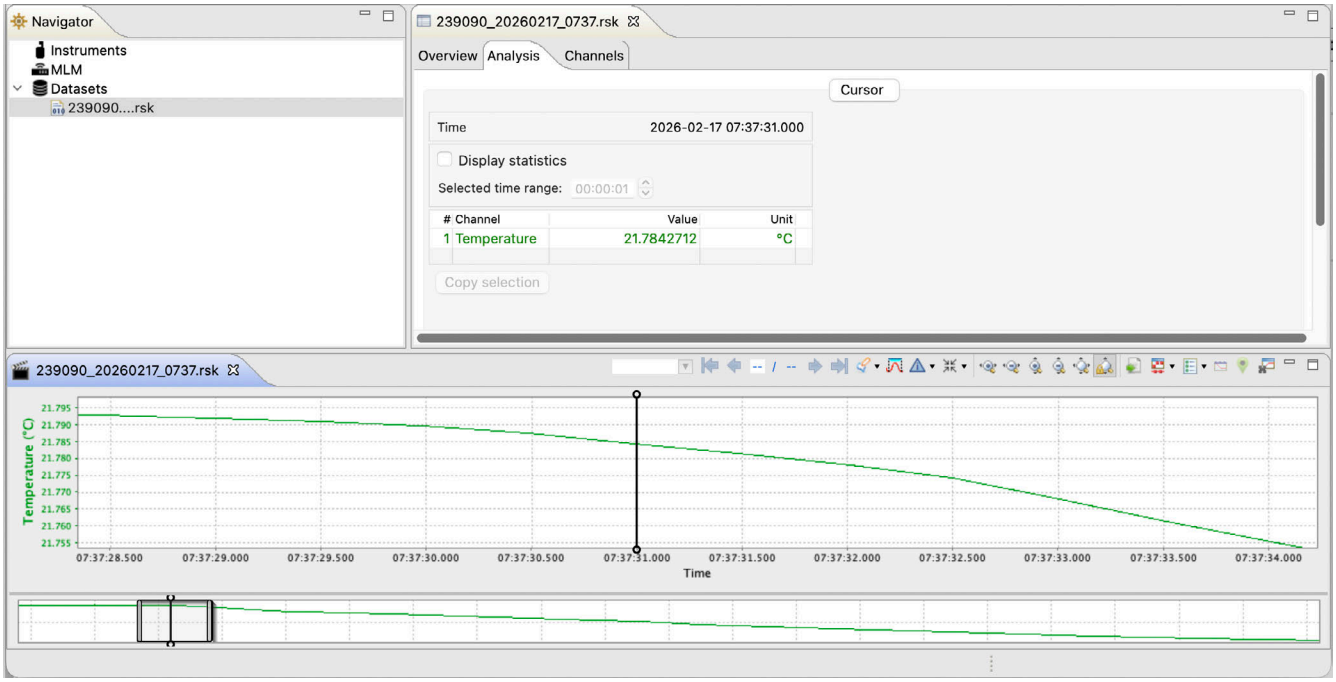
The **Analysis** view contains statistical information about deployment, as well as information about the dataset channels and their values.

The colour-coding of the channel table matches that of the traces in the **Plot** window. To change the colour settings for your chart, go to **Preferences > Plotting > Channel colours**.



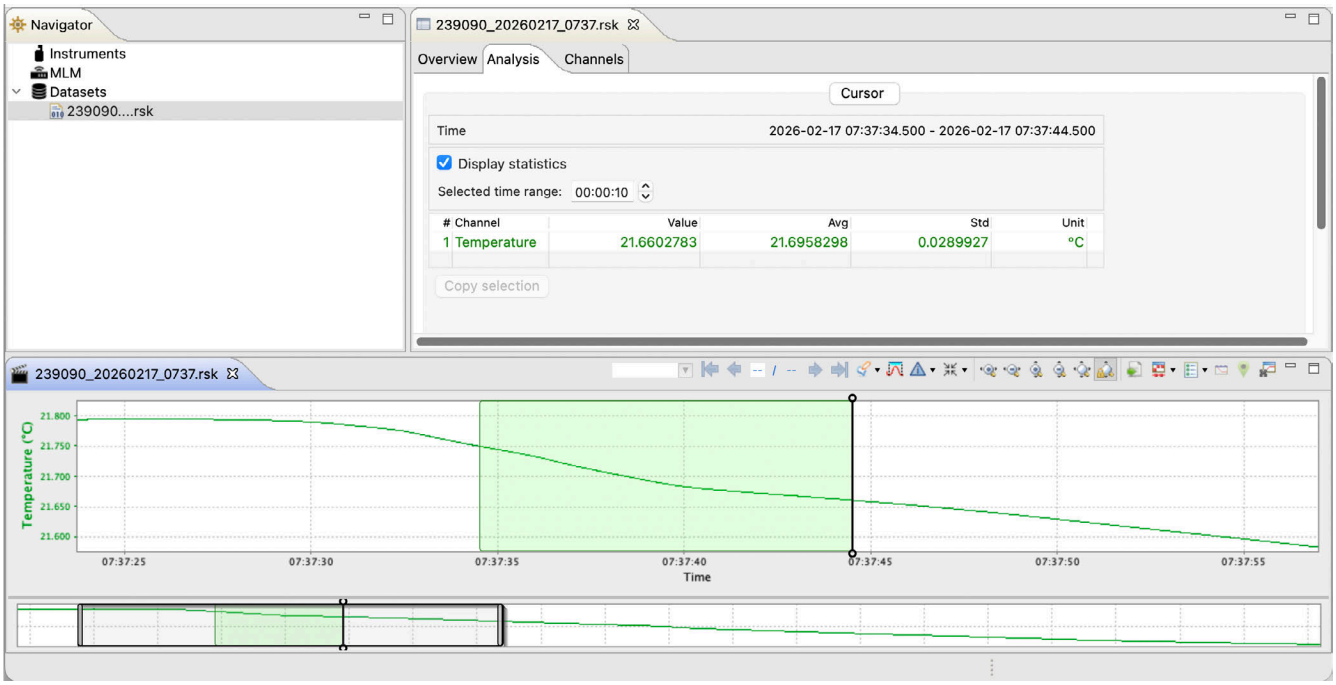
Move the black cursor ("double lollipop") in the **Plot** window to display parameter values for each sample selected.

Every time you move the black cursor, going from sample to sample, the table above the plot will display the information for this particular sample.



Select **Display statistics** checkbox to determine the average value and standard deviation over a range of samples. Change the **selected time range** of samples to average using the up and down arrows or by clicking in each of the hour, minute, and seconds fields to edit the time manually.

The table will display the averaging data. The averaging interval will be highlighted in the plot.

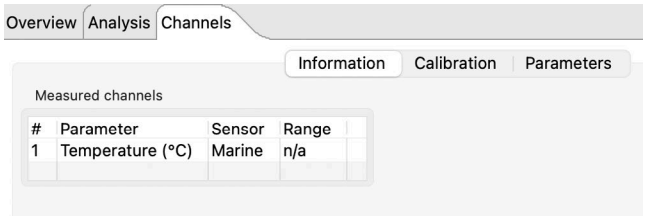


12.4 Overview

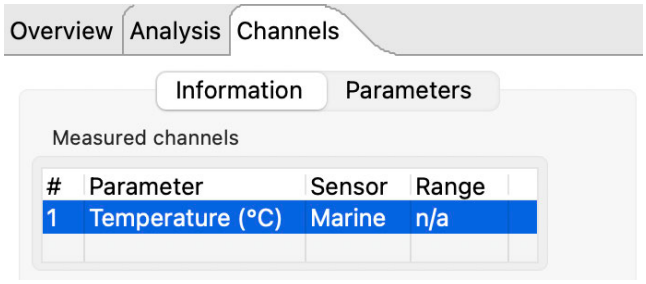
Use the **Overview** tab to view general information for each dataset, including instrument firmware and serial number, enabled schedules, deployment events, and details about the file itself.

12.5 Channels

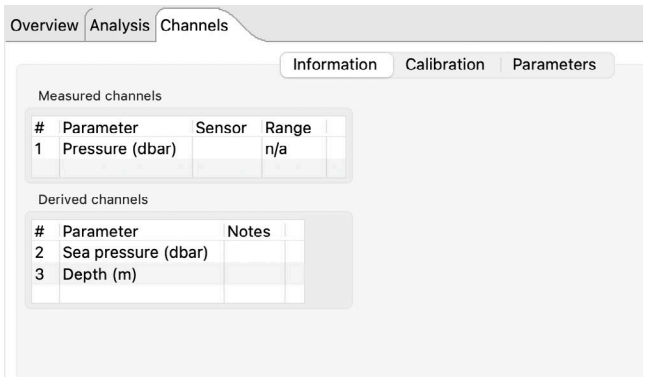
For, non realtime datasets, the **Channels** tab will have three options: **Information, Calibration,** and **Parameters**.



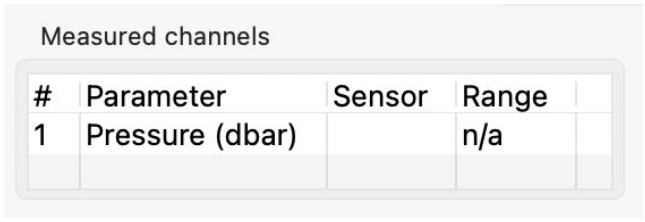
For realtime datasets, the **Channels** tab has two options: **Information** and **Parameters**.



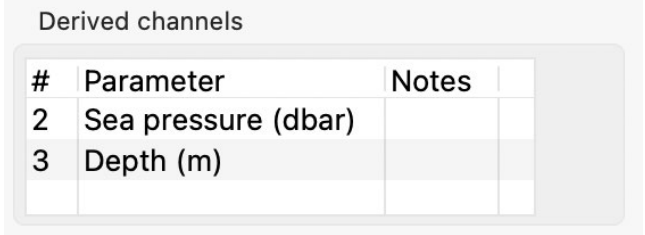
The **Information** page displays two tables: **Measured channels** and **Derived channels**.



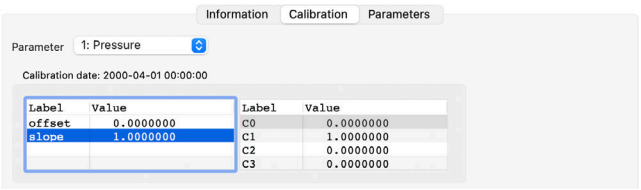
Measured channels include measured parameters with their units of measurement, the sensor manufacturer, and the range setting (if applicable).



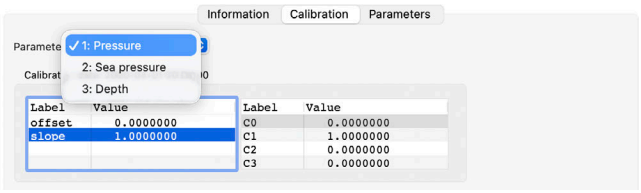
Derived channels include all available derived parameters with their units of measurement and the methodology used to calculate them.



The **Calibration** page displays the calibration and correction coefficients (as applicable) for each channel, along with the date and time of the last calibration.



Select a sensor from the **Parameter** dropdown menu to display its calibrations.

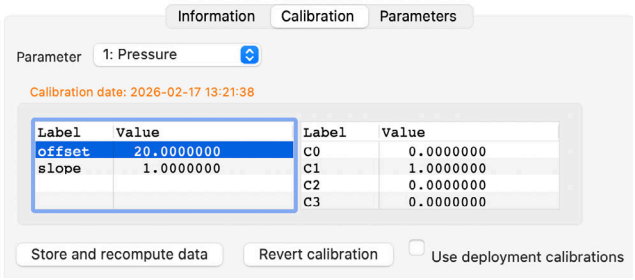


The main calibration coefficients are displayed as "C" values: C0, C1, C2(K). Dependent coefficients are displayed as "X" values: X0, X1, X2, etc.

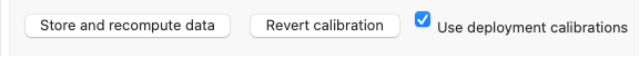
> Both **offset** and **slope** are editable in any dataset format. Other coefficients are only editable when recorded in **calibration** mode.

As soon as an edit is made to a coefficient cell and another cell is selected, a new calibration date will be displayed. Also, all three buttons at the bottom of the page will become active.

Use **Store and recompute data** to recalculate the dataset. Use **Revert calibration** to restore the previous coefficients that were not saved.



To restore the calibration used during the deployment, if a new calibration has been stored, check the **Use deployment calibrations** checkbox. Click **Store and recompute data** to save the coefficients as the latest.

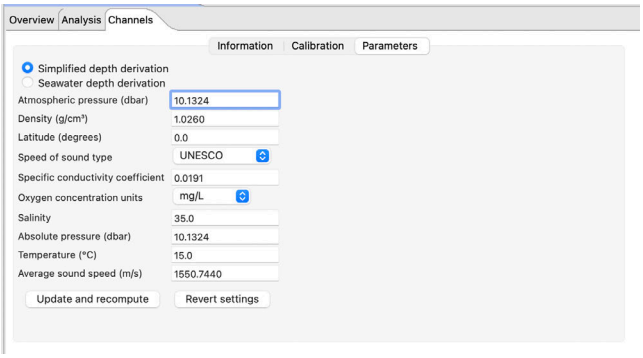


The **Parameters** tab displays parameters necessary to calculate derived channels and the method used for calculation.

You can edit these parameters to change the derived channel calculation. As soon as you make a change, the two buttons at the bottom of the page will become active.

Click **Update and recompute** to recalculate the data and display new values.

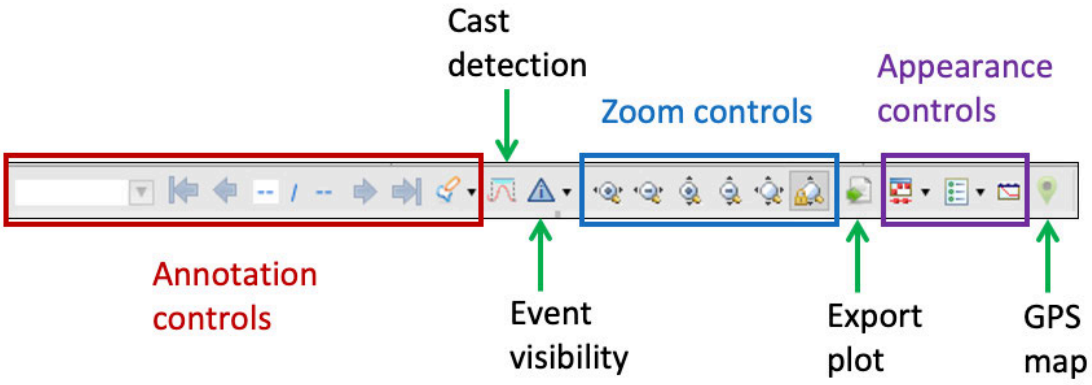
Use **Revert settings** to recover the previous coefficients and data if you have not already selected **Update and recompute**.



> This page is not editable for realtime datasets.

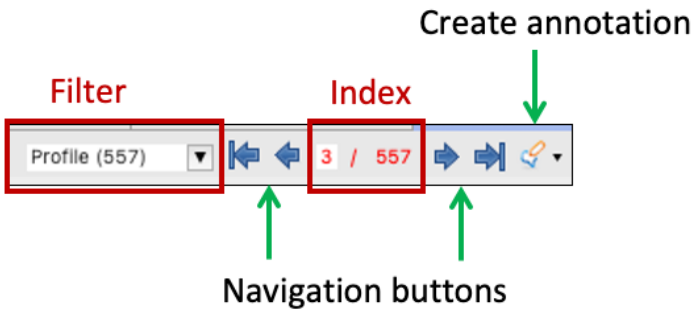
13 Dataset plot toolbar

Use the plot toolbar to adjust the display of an open dataset.



13.1 Annotation controls

Annotations are information messages added either by users or by the instrument.

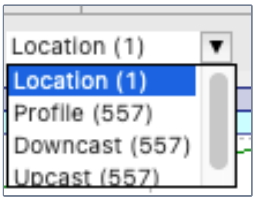


13.1.1 Select annotation type

Annotation types are divided in two categories: profiling (**Profile**, **Downcast**, or **Upcast**) or non-profiling (**Comment**, **Exclusion**, **Location**, or **Calibration**). Use annotation controls to manage this information and to navigate the plot.

Type	Function
Profile, Downcast, Upcast	Identify profiling
Comment	Add a note to your data
Exclusion	Remove a non-representative interval from analysis
Location	Add in latitude/longitude coordinates for RSK files to track locations of data logging
Calibration	Calibrate the ODO sensor

Open the **Filter** dropdown menu to select the annotation type to display. The number of annotations for each type will be indicated.



Select an annotation type. The plot will centre on the first item in the selected category. For example, when you select **Profile**, the plot will move to the first profile.

If you switch the filter to another annotation type within the same category (for example, **Profile** to **Upcast**), the plot will not change. If you switch to a type from another category (for example, from **Profile** to **Comment**), the plot will move to the first annotation in the new category (for example, to the first comment).

13.1.2 Navigate between annotations

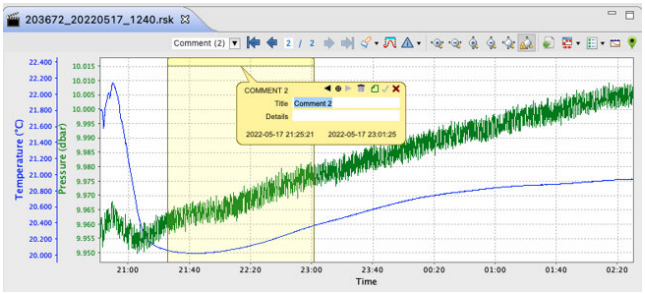
Use the **Navigation** buttons 

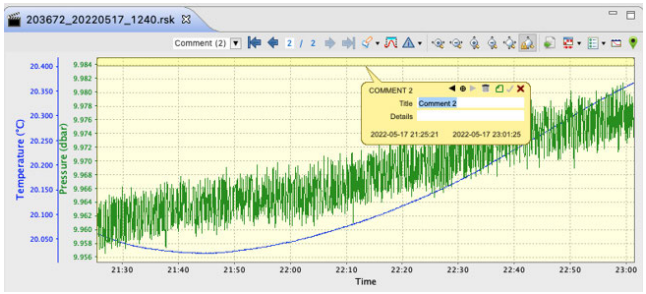
to navigate between items within the selected category.

> The navigation buttons will be activated if there is more than one item in the selected annotation type. Otherwise, the plot will centre on the only item available.

Navigation controls

- Move from one annotation to another by clicking the **left** and **right** arrows.
- Jump all the way to the beginning or end of the list by using the **end-left** and **end-right** arrows.
- Alternatively, manually enter the number in the **Index** field to go to that particular annotation.
- Double-click an annotation to centre and zoom in the plot at that particular area.





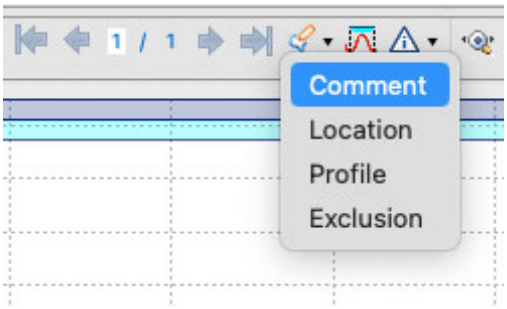
> Double-click anywhere on the main plot to return to the full-chart view.

13.1.3 Create new annotation

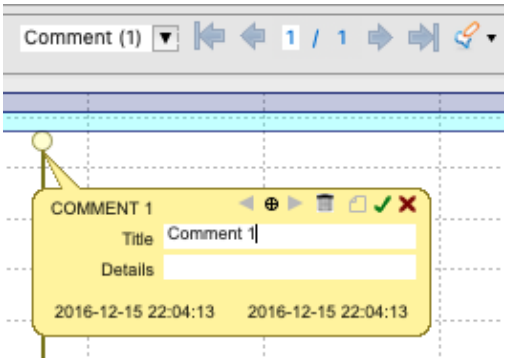
Click the **Create annotation** button  and follow the steps below.

Steps

1. Select the type of annotation to create, for example, **Comment**.
   The cursor in the **Plot** window will become a two-way arrow ↔.



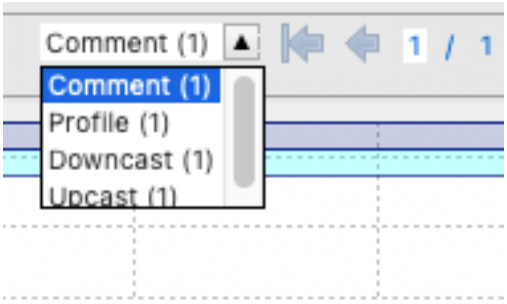
2. Click on the main plot to identify a single point to comment, or click and drag the cursor left or right to select an interval. When you release the click, an editable tooltip will open.



The tooltip controls include **Left** and **Right** arrows ◀ ⊕ ▶, **Delete** 🗑, **Export region** 📄, **Save** ✓, and **Close** ✗.

The **Profile** tooltip also features **Up** and **Down** arrows ▼ ▲ for adding upcast and downcast profiles.

3. Enter the necessary information into the fields and save by pressing **Enter** on your keyboard or by clicking **Save** ✓ on the tooltip. Your new comment will appear in the dropdown list.



- Clicking **Close** ✗ or pressing **Esc** on the keyboard will close the tooltip without saving.
- Click the **arrows** ◀ ⊕ ▶ on the tooltip to move to the next annotation within the same category.
- Double-click on the annotation bar to zoom in to the range of the annotation.
- Click and drag on the annotation bar to move the annotation.
- Click **Delete** 🗑 on the tooltip to delete the annotation. A warning message will appear.
- Click **Delete** to proceed. This action cannot be undone.

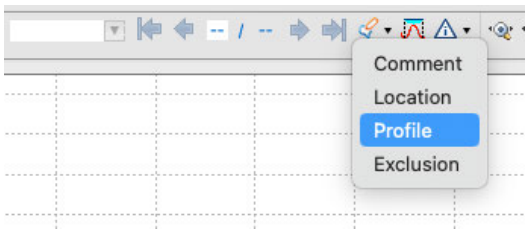
Edit at least one detail in the tooltip before saving. Otherwise, the annotation will be deleted when deselected. Moving or resizing the annotation counts as editing and saving.

13.1.4 Add profiles

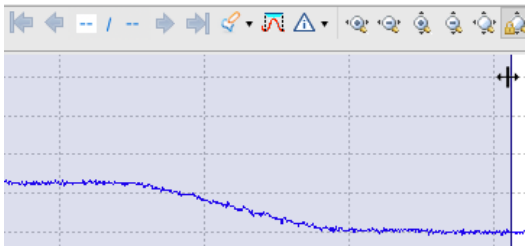
Use the **Annotation** function to manually add profiles to your dataset.

Steps

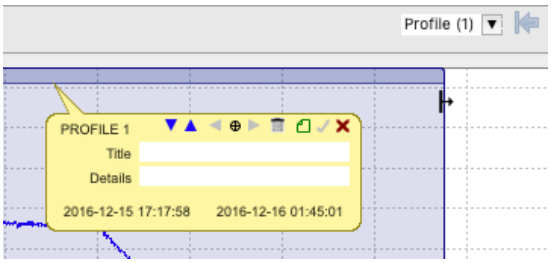
1. Click the **Create annotation** button 
and select **Profile** from the dropdown menu.



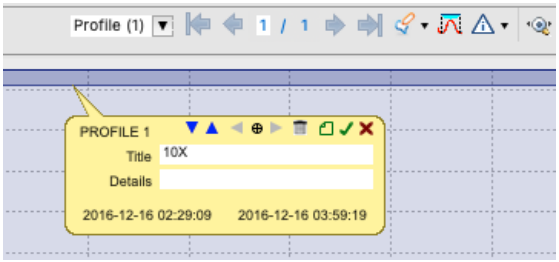
2. Click and drag the cursor to select a region. As soon as you let go, an editable tooltip will open and a band of a darker colour will appear above the selection, indicating that a new profile has been added.



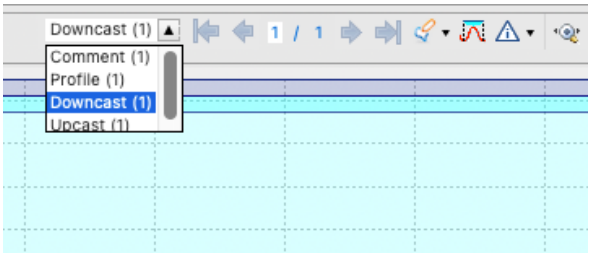
3. Place the cursor on the edge of this new profile and move it left or right to adjust the size.



4. Add a name and click **Save**  on the tooltip.

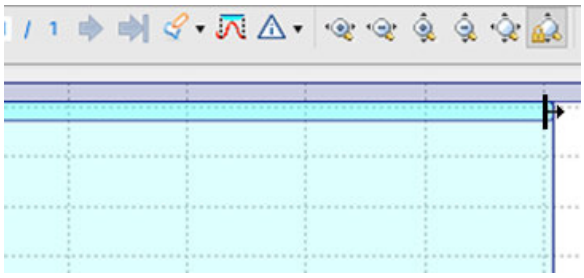


5. Use the **Up** and **Down** arrows on the tooltip to identify upcast and downcast regions.
   The upcasts and downcasts you added will be displayed in the dropdown menu and highlighted on the plot under the parent profile.

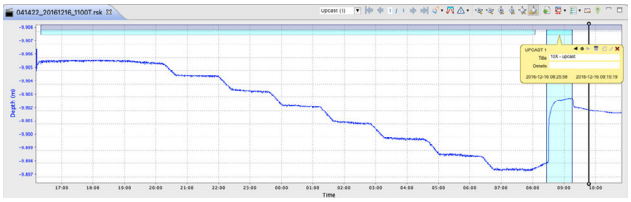


⚠ Only the **Profile** tooltips have the **Up** and **Down** arrows.

6. Place the cursor at the edge of the added region and adjust its size.



7. Click on a profile/upcast/downcast to open its tooltip.
8. Name each region and save the settings.



9. If desired, export your profile to a separate RSK file. To do that, click **Export region** on the **Profile** tooltip and follow the steps.

⚠ The **Export region** option is not available on **Upcast** and **Downcast** tooltips. To generate an RSK file for an upcast or downcast section only, use the **Comment** annotation to clip the dataset before exporting.

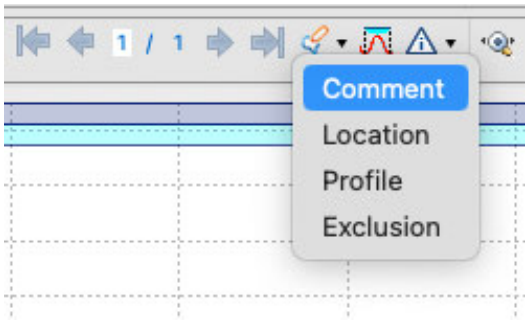
13.1.5 Export region

⚠ The **Export region** option is only available for **Comment** and **Profile** annotations.

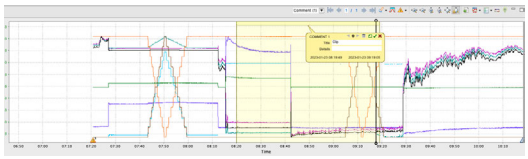
Follow the steps below to clip your dataset and export a subset of your data. This function may be useful when you need to exclude certain regions. For example, a dataset may contain several deployments if sampling was not paused/stopped before the new deployment was started.

Steps

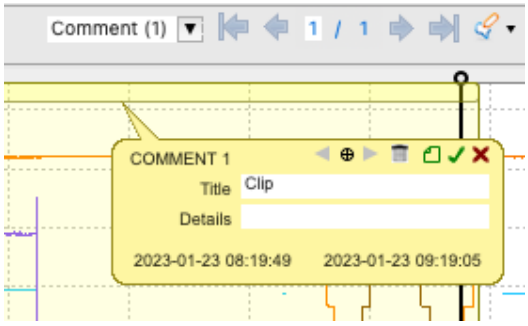
1. Click the **Create annotation** button and select **Comment** from the dropdown menu.



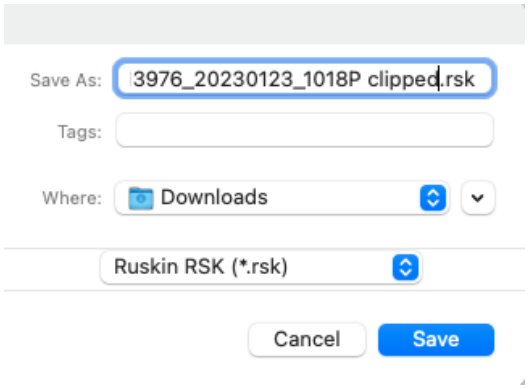
2. Click and drag the cursor to select a subset.



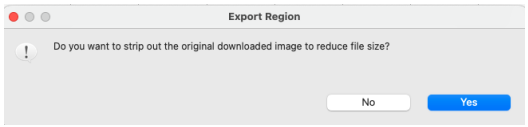
3. Enter a name in the **Title** field on the tooltip and click **Save** .



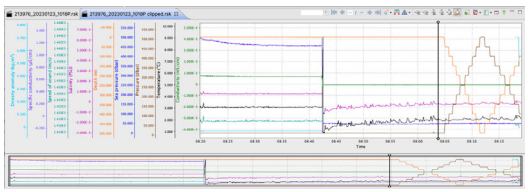
4. Select **Export region** on the tooltip.
A dialogue box will open.



5. Adjust the name and location for the new dataset file and click **Save**.
An **Export region** message will appear.



6. Select **No** to maintain the full binary values and retain the option of recalibration in the future.
The clipped dataset will open in a new tab in the **Plot** window.



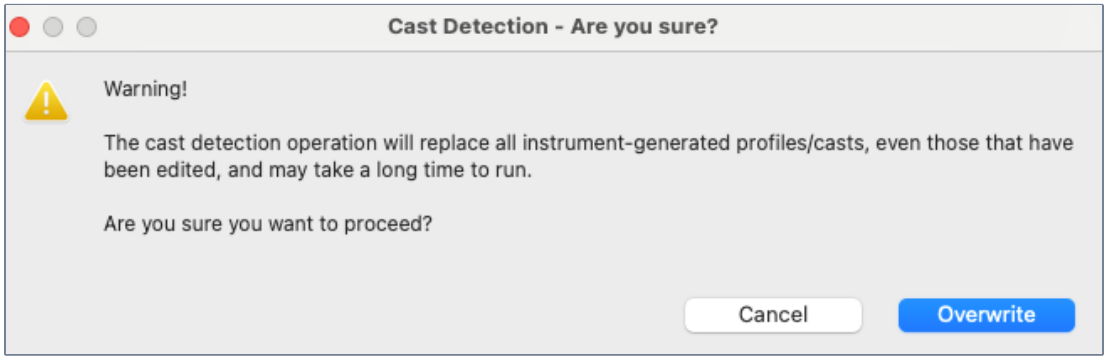
13.2 Cast detection

Ruskin automatically enables profile detection on instruments when a deployment is enabled. There are several criteria for enabling this feature.

- The instrument must support the `castdetection` setting
- The instrument must have a pressure sensor
- The deployment must be configured for | fast sampling (2Hz and up)
- The deployment mode must be configured as either continuous or directional

It is possible to recalculate the casts in a dataset using the cast detection feature in the **Plot** view.

Click the **Cast detection** button  to run a cast detection algorithm based on depth and conductivity to automatically generate profiles and casts. A warning message will appear.

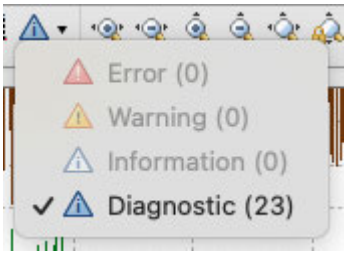


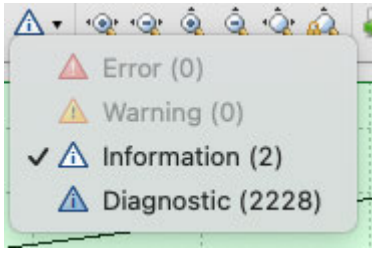
If you proceed, Ruskin will find peaks, collect events, and overwrite profiles recorded by the instrument.

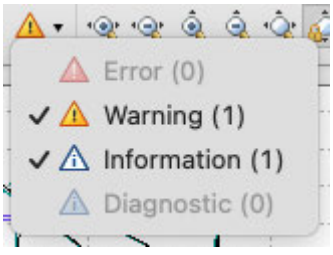
Double-click anywhere on the main plot to return to the full-chart view.

13.3 Event visibility

Click the **Event visibility** button  to turn on and off the visibility of the various levels of events: **Error**, **Warning**, **Information**, and **Diagnostic**. Its colour will reflect the highest level of event severity reported.

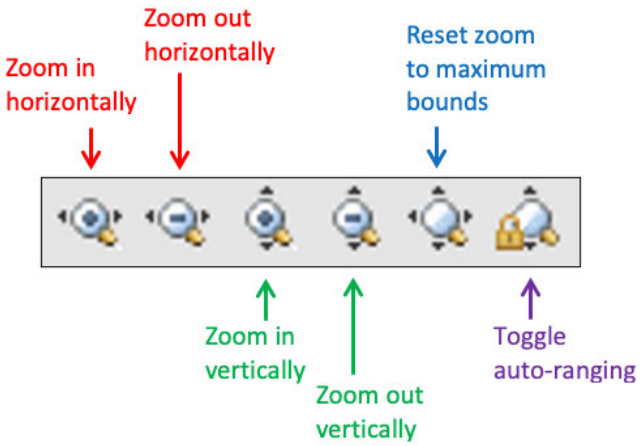






13.4 Zoom controls

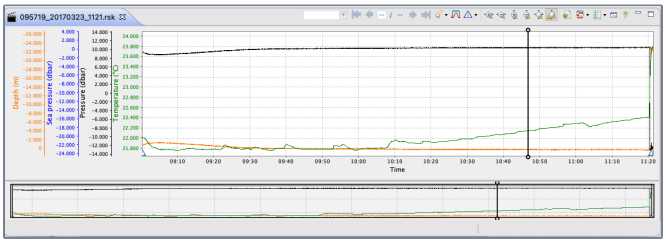
Default scaling of the plot is based on the minimum and maximum values sampled for each channel. Use zoom controls to adjust it as needed.



Double-click anywhere on the main plot to return to the full-chart view.

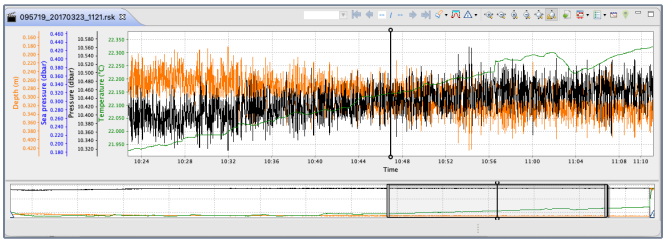
13.4.1 Horizontal zoom

Horizontal scale options may be helpful to increase or decrease the the time range displayed. It is convenient when the dataset is long and thus losing resolution when displayed in the **Plot** window in its entirety, like in this example.



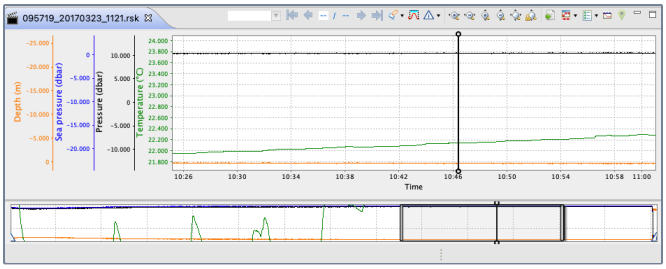
There are three ways to apply changes to the horizontal scale. The first two will auto-range your chart, ensuring the entire vertical domain is visible. The third approach will retain the latest vertical scaling of the original interval.

1. Use the **Zoom in horizontally** and **Zoom out horizontally** buttons.
   OR
   Click on the thumbnail view and resize the indicator. The vertical scale will automatically adjust to fit the new range.



2. Hover your mouse over the X-axis, then hold **Shift** + **left click.**

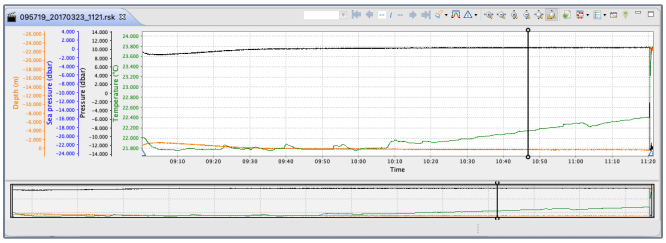
   The cursor will change to a two-way arrow ↔. Drag it right to zoom in or left to zoom out the time domain, without changing the data resolution.



Click **Reset zoom to maximum bounds** or **double-click** anywhere on the chart to restore the original appearance.

13.4.2 Vertical zoom

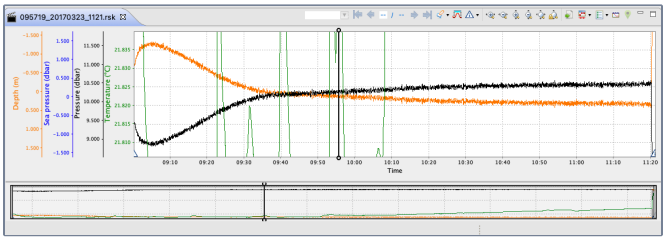
Vertical scale options may be helpful when there are erroneously high or low values that make the real data appear incorrect, or when there is significant difference in scale between the displayed parameters.



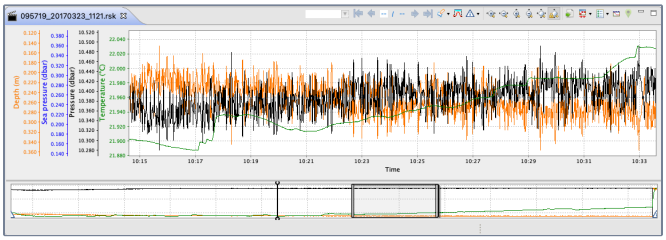
Entire chart

Depending on the zooming method, you may change the scale only vertically, or both vertically and horizontally.

- Use the **Zoom in vertically** and **Zoom out vertically** buttons to increase or decrease the resolution of the data displayed.
  The resulting display will retain the same horizontal scale.



- Hover the cursor and scroll your mouse wheel up and down to change the scale.
  In this case, the horizontal scale will also change (as seen from the thumbnail indicator). The plot will centre where the mouse cursor initially was.

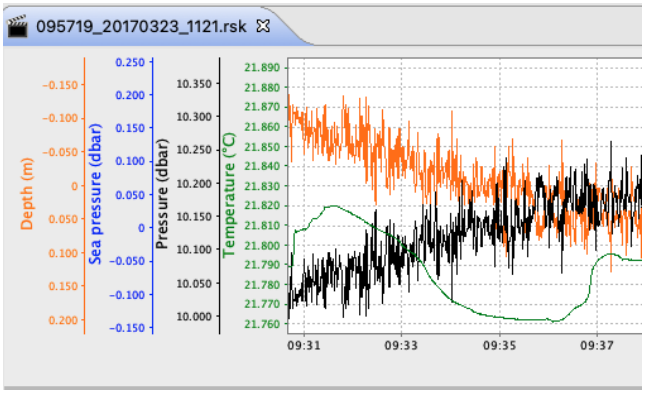


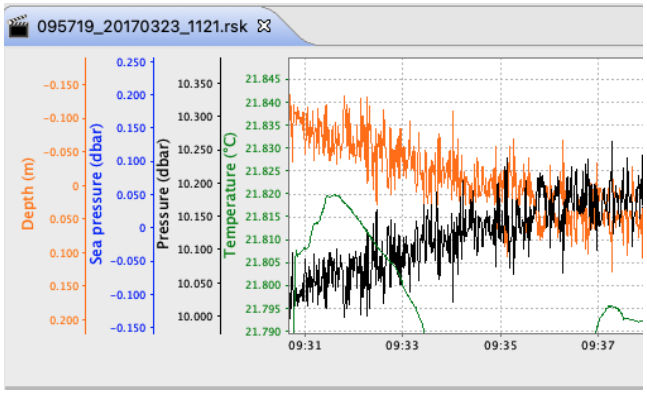
Individual channel

There are two ways to apply changes to the vertical scale of one channel only, which yield the same results.

- Hover the cursor over the Y-axis for this channel and scroll your mouse wheel up and down.
- **Shift** + **click** the Y-axis for this channel and move your mouse up and down.

This particular channel will zoom in and out (in the example below, temperature). Double-click on the same vertical axis to reset this parameter.



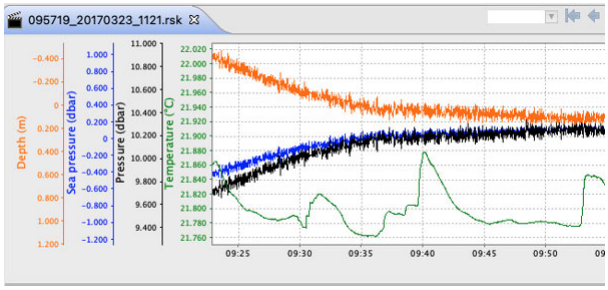


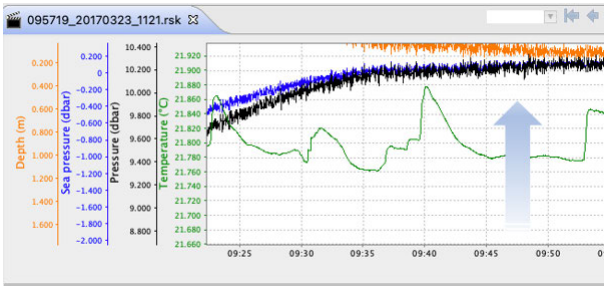
Click **Reset zoom to maximum bounds** or **double-click** anywhere on the chart to restore the original appearance.

13.4.3 Navigation options

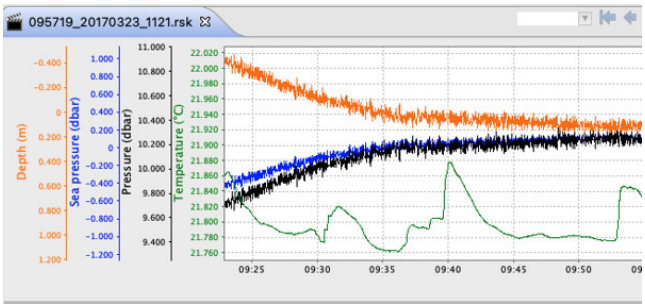
After you change the scale, some parts of your chart may end up outside the **Plot** window. There are several options available to navigate it.

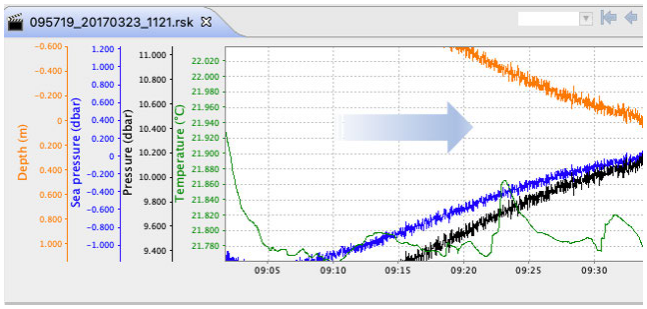
- To pan the entire chart horizontally, hold **Ctrl** + **left click** and move your mouse left and right. This action is only possible after already applying some horizontal zoom to the chart.



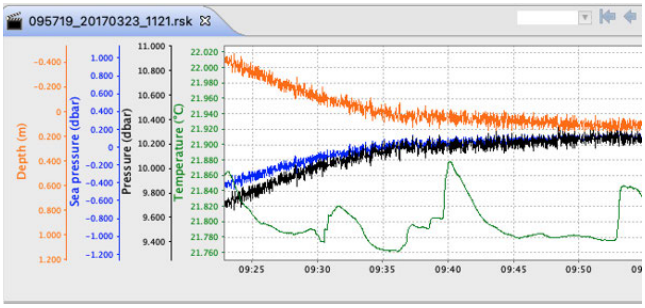


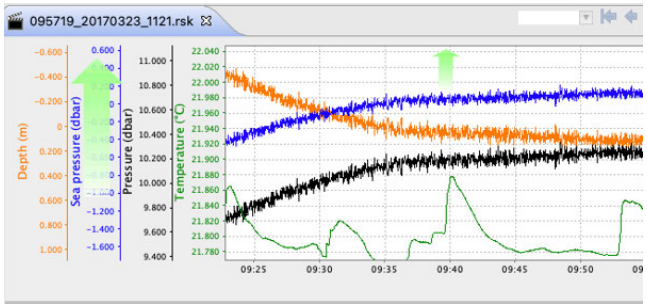
- To pan the entire chart vertically, hold **Ctrl** + **left click** and move your mouse up and down.





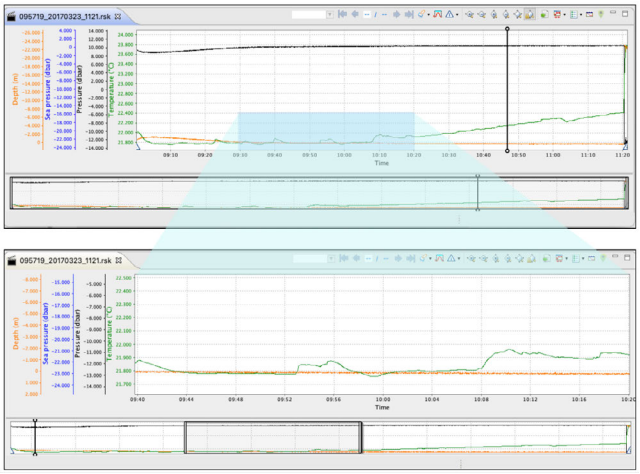
- To pan one of the channels vertically, click a value on the vertical axis for that parameter (in the example below, sea pressure) and move your mouse up and down.



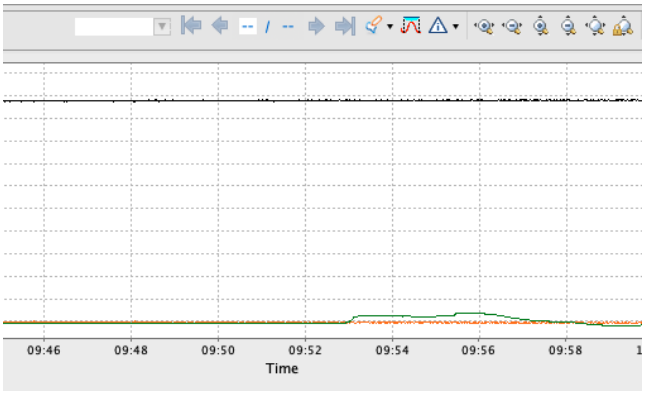


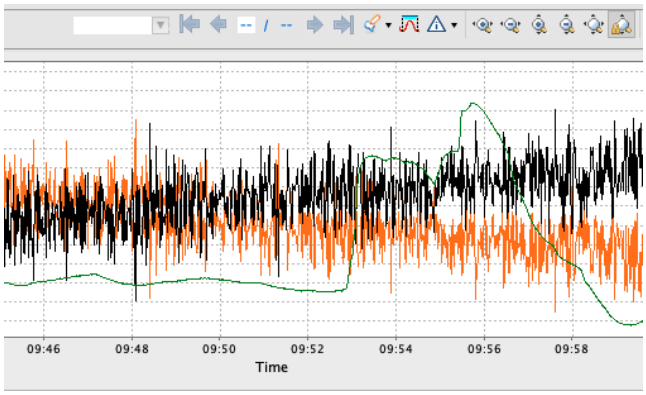
Double-click on the same vertical axis to reset this parameter.

- To freely select any part of the chart, hold **Shift** + **left click** and draw the rectangle. The chart will zoom in on the selected area, both horizontally and vertically.



- To keep all your data within the viewing window, click the **Toggle auto-ranging** button  . When it is on, all profiles within the selected time section maintain their optimal vertical zoom.





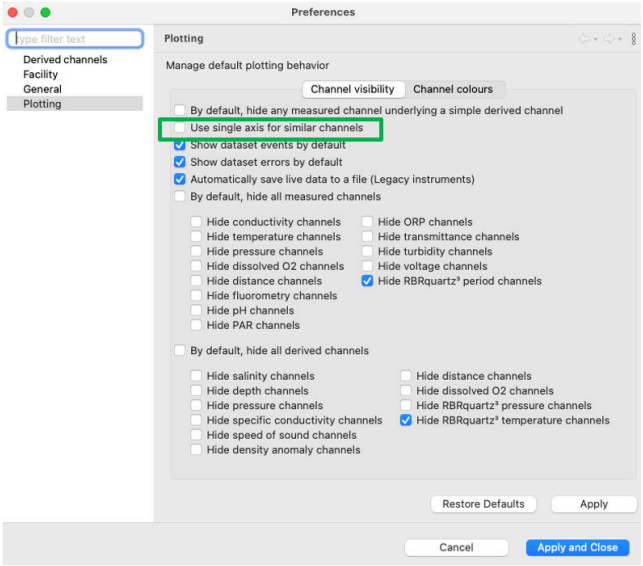
- Click again to disable. Disabling the auto-ranging of the axis can be useful for looking at trends in data. Zooming in or out of an individual channel will disable auto-ranging for that channel.
- To zoom in to the range of an annotation, double-click on the annotation bar.

Click **Reset zoom to maximum bounds** or **double-click** anywhere on the chart to restore the original appearance.

13.4.4 Advanced axis controls

By default, Ruskin will use a single axis to display similar channels. To display each similar channel on its own axis, go to **Settings** > **Plotting** > **Channel visibility**. Deselect the **Use single axis for similar channels** checkbox.

Click **Apply and close**. These changes will automatically apply to every new dataset. To apply your changes to an active dataset, close it and then re-open.



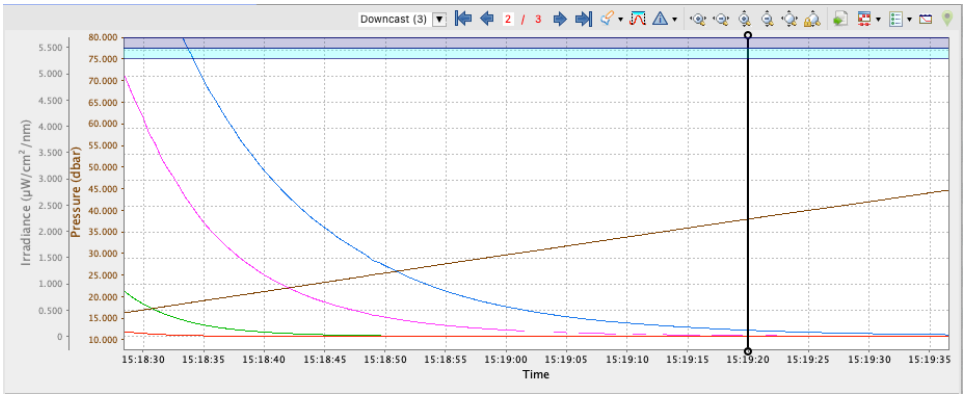
Both views have their advantages. Below, compare the two displays of the same dataset obtained using an RBR*quadrante* .

Default settings: single axis

The chart displays four irradiance channels and one irradiance axis. The axis is grey, while the traces related to this single axis remain colour-coded.

With the axis panel collapsed, you have a broad view of the chart.

All four channels have the same scale, which in the example below is 0-5.500µW/cm²/nm. Vertical zoom controls, if used, are applied to all these traces as a group.

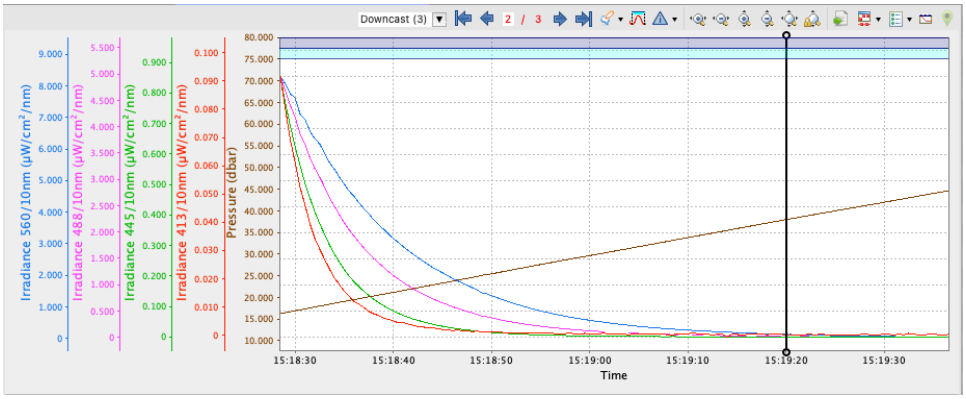


Customised settings: multiple axes

The chart has four irradiance channels and four axes, each identified with the same colour as the trace. The corresponding wavelength and FWHM will also be displayed; in this example: **560/10**, **488/10**, **445/10**, and **413/10**.

Each channel has its optimal vertical scale. In the example below, the scale for the **560/10** is **0-9.000µW/cm²/nm**, while for the **413/10** it is **0-0.100µW/cm²/nm** .

To adjust the vertical scale for each channel individually, hover the cursor over an axis and scroll your mouse wheel up and down. See **Vertical zoom** for other ways to adjust the scale.



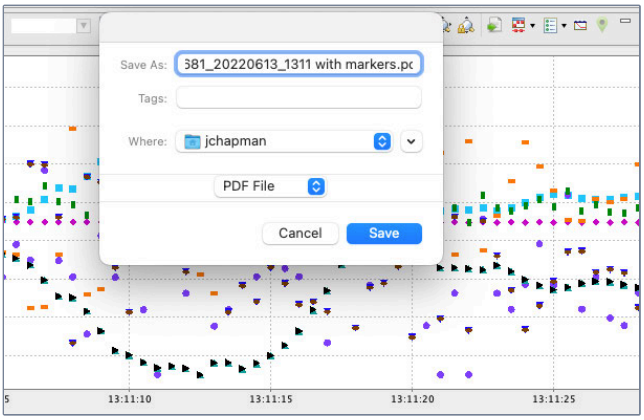
Regardless of the view (single axis or multiple axes), the channel table in the **Analysis** tab retains individual colours for all channels, matching the colour-coding of the traces in the **Plot** window.

7	Irradiance 413/10nm	4.9941950	µW/cm²/nm
8	Irradiance 445/10nm	11.2594115	µW/cm²/nm
9	Irradiance 488/10nm	18.3235068	µW/cm²/nm
10	Irradiance 560/10nm	15.9567764	µW/cm²/nm

To change the colour-coding settings for your chart, go to **Settings** > **Plotting** > **Channel colours**.

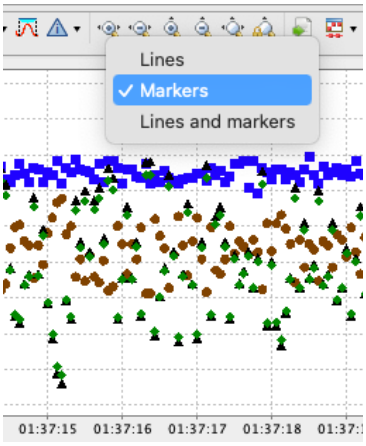
13.5 Export plot

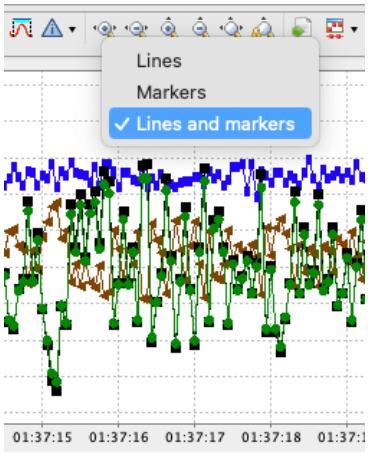
Click the **Export plot** button  and select file name and location to save the current view of the main plot to a PDF or PNG file. The exported file will contain the graph only and retain all the changes to display active at the moment of export: zoom, lines and markers, visible events and annotations, and plotting by depth or time.



13.6 Appearance controls

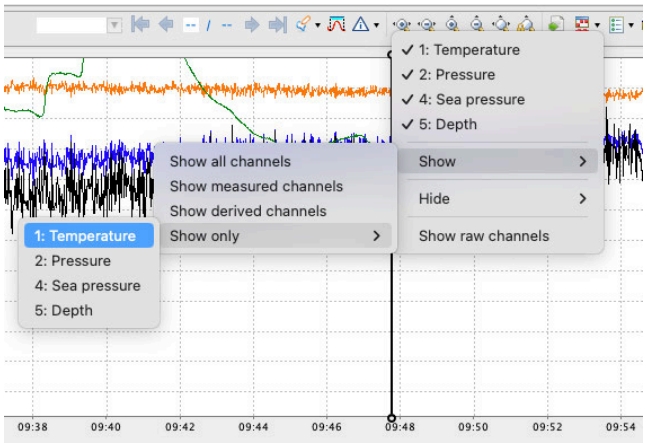
Select your data rendering type from the **Change line type** dropdown menu  : **Lines**, **Markers**, or **Lines and markers**.



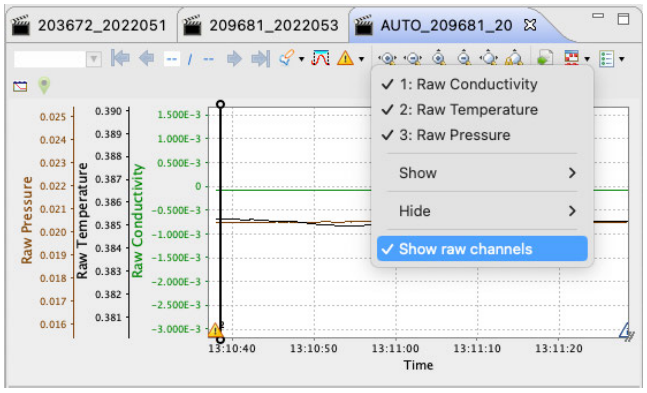


If no data appears in the **Plot** view, try changing the rendering to **Markers**. Time spans that are larger than expected will cause breaks between data points and lines will not be drawn connecting those points, whereas markers draw at each individual point.

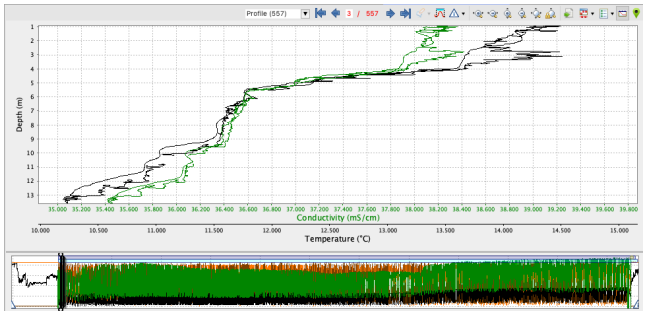
Use the **Toggle channel visibility** button to open the dropdown menu with the list of available channels and options. Check and uncheck channels to display as desired, or select groups to show and hide.



Select **Show raw channels** to display measured data with no calibration equations applied.



By default, the data are plotted by time. Use the **Toggle depth plot** button to switch to the plot-by-depth mode.

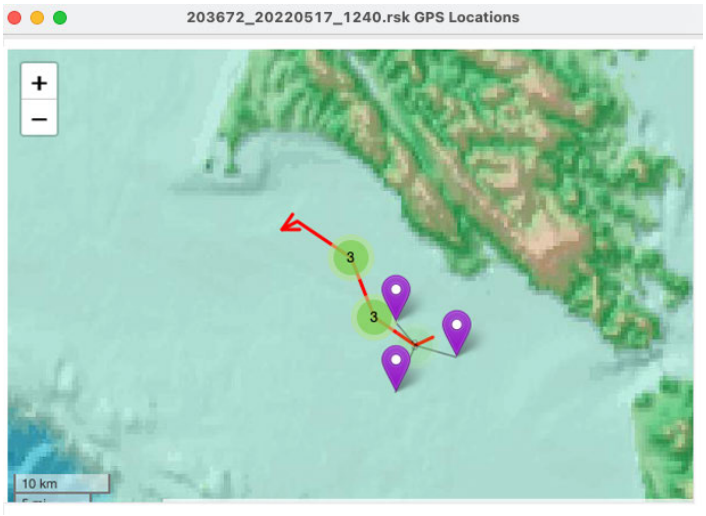


The thumbnail view will continue to display the plot-by-time data.

> If there is no depth channel, the plot will use the next pressure or pressure-derived channel starting from the bottom of the channel list.

13.7 GPS map

The **Show GPS map** button opens a pop-up window with the GPS map for the plot. Click on the map to display all the GPS location annotations recorded in the dataset.



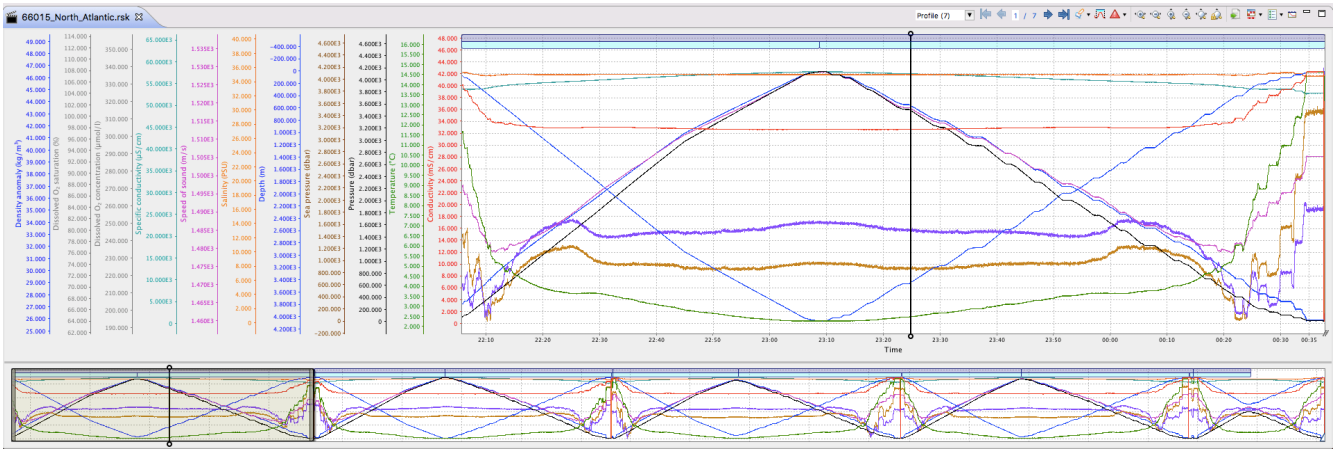
GPS mapping for Desktop RSK files relies on manually added location points (see Annotation controls). All location points you added using the **Annotations** feature are stored in the dataset file and can be displayed in Ruskin via the mapping functionality.

> Charting and continuous GPS tracking are only available on the Ruskin Mobile app, for datasets in the **Mobile** storage format.

14 Plot window

Use the **Plot** window to view graphical displays of your datasets or live data. When viewing live data, the instrument must be attached.

Each channel appears as a different colour in the plot. These colours are specified under **Settings** > **Plotting** and can be changed only there.



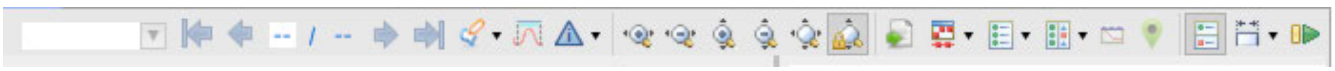
Move the black "double lollipop" cursor from one sample to the next to display parameter values for each sample selected. Drag it with your mouse, or use the arrow keys on your keyboard as follows:

- To move by one data sample, press **right** or **left arrow**
- To move by a hundred of samples, press **Shift + right arrow** or **Shift + left arrow**
- To move by ten thousand of samples, press **Alt + right arrow** or **Alt + left arrow**
- To move by millions of samples, press **Shift + Alt + right arrow** or **Shift + Alt + left arrow**

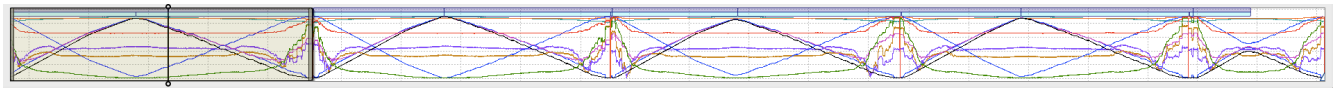
For the datasets, these values will appear in the **Properties** window above (see **Analysis**). For live data, they will be on the side of the plot.

The graphical display for each dataset or instrument will be in its own tab. The dataset file name or the instrument model and serial number will appear at the top of the tab. Simulated instruments will have "sim" in front of their name.

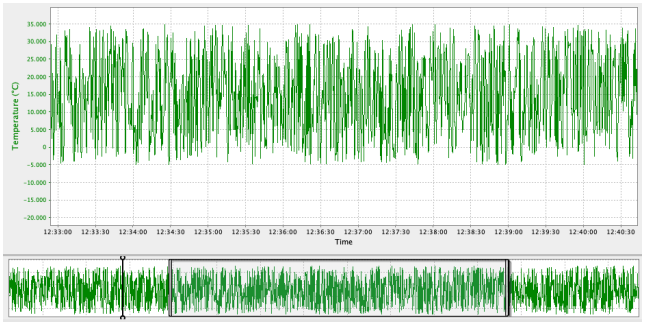
A toolbar at the top right of the **Plot** window contains various buttons to help you customise, explore, and export the graphical display. The buttons selection changes depending on what is displayed in the tab. Hover over a button to display its name and function.

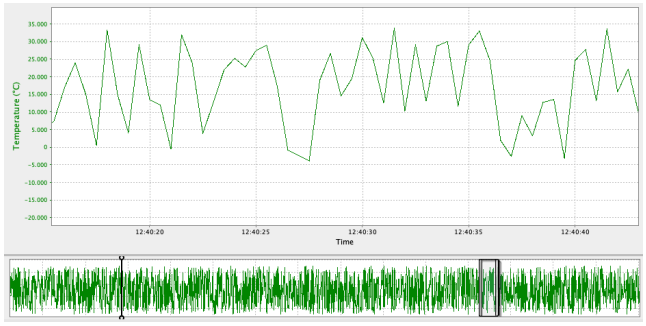


A downsampled representation of the dataset appears in the thumbnail view, along with an indicator of the current plotted time range.



Position the indicator by clicking on the thumbnail view and dragging the indicator. Resize the indicator by dragging the edges left and right. It will zoom the main plot along the time domain to match the new indicator size. See **Zoom controls** for more scaling options.





The thumbnail view always shows the plot-by-time data, even if the plot is switched to the plot-by-depth mode.

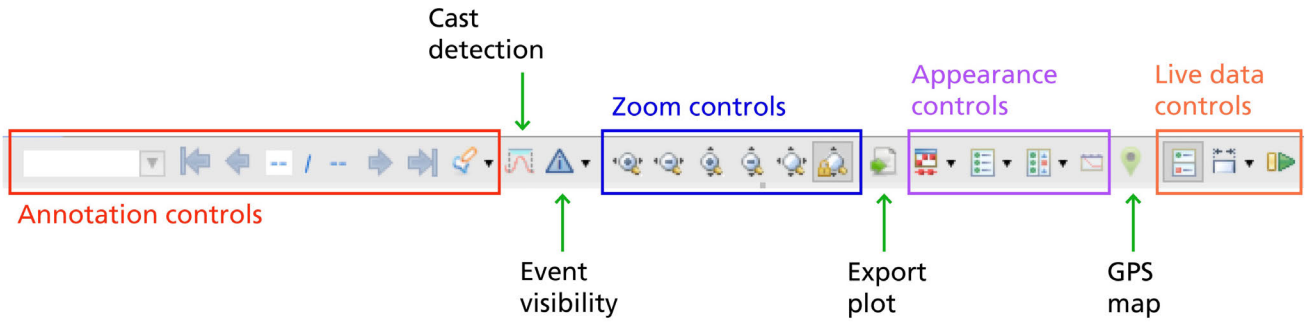
When you close and re-open a dataset, it will retain your latest settings (channel visibility, zoom, plot style (plot-by-time or plot-by-depth), annotation selection, and display style (lines or markers).

Double-click anywhere on the main plot to return to the full-chart view.

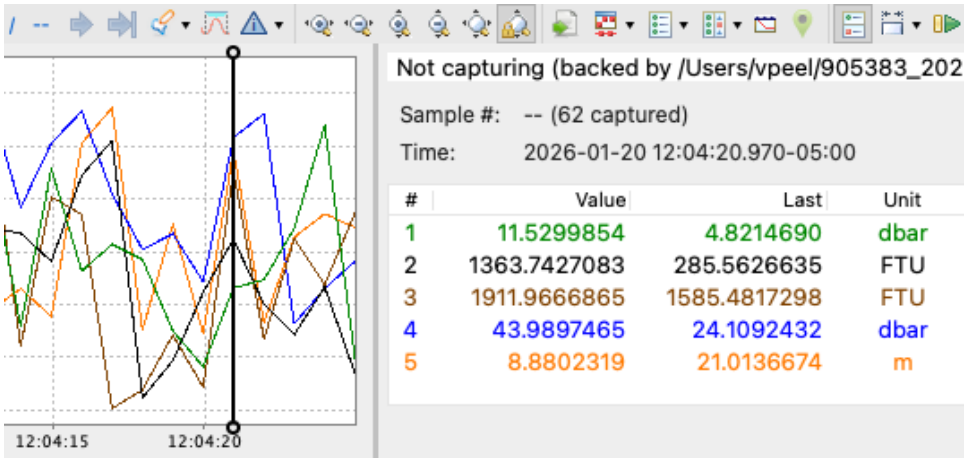
Go to **Appearance controls** to change your selection of lines and markers.

15 Live data plot toolbar

You can use the **Plot** window to view a live graphical display of your instrument sampling. All options described in the **Dataset plot toolbar** section apply to live data display. Additionally, three live data buttons appear at the right end of the toolbar: **Side data panel**, **Live plot time range**, and **Poll**.

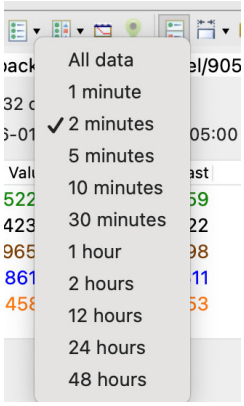


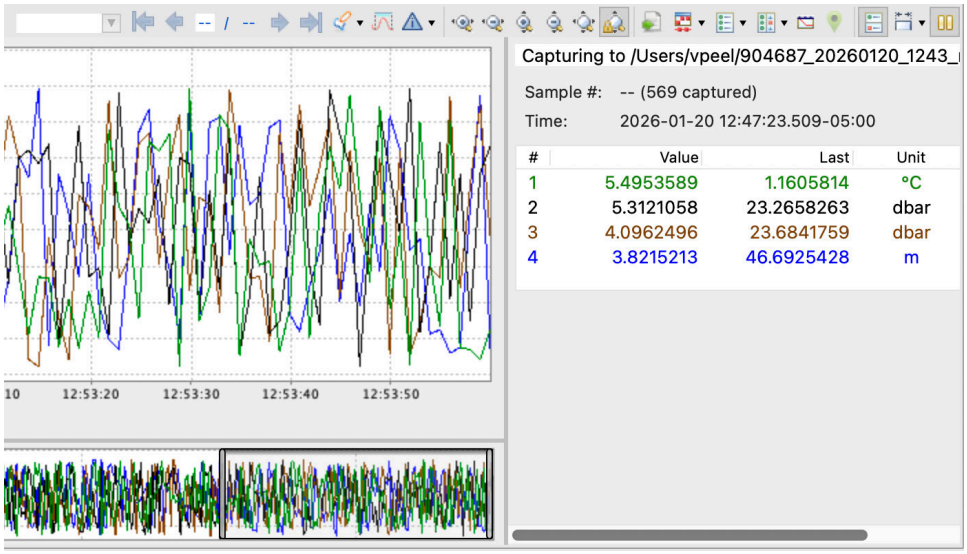
Click the **Sample display** button  to toggle on and off the data panel to the right of the plot. It shows the file location that will be used to capture samples, the number of samples collected, the values of the last received sample, and the currently selected sample.



Click the **Live plot time range**  button to open a dropdown list of time span options.

For example. select **2 minutes** to display the data in the thumbnail view and on the side panel by two-minute time periods.





You can also choose to display all of the data collected.

Polling

Live data can come from one of two sources: streaming or polling.

Polling is the action of asking the instrument to take a reading and report it.

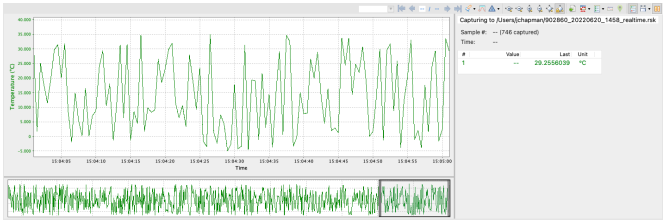
Polling can be used on an instrument that is either not enabled or enabled without a streaming option. To disable the streaming option, go to **Options** under the **Configurations** tab and set **Realtime** to **None**.

Click the **Poll** button to start polling data. The button will change to **Pause**. Click the **Pause** button to stop polling.

> If streaming is selected (**Realtime** is set to **Serial** or **USB**), clicking the **Poll** button will have no effect on the plot.

If the instrument is polling data, but you want to start streaming, go to **Options** under the **Configurations** tab and set **Realtime** to **Serial** or **USB**, then click **Enable.**

Ruskin will disable polling, close the current dataset used for the polled data, and create a new file for the streamed data. A new streaming plot will appear. Click the **Pause** button to freeze the view of live data.

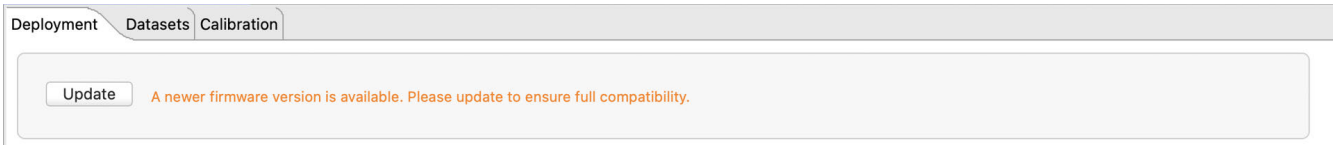


16 Firmware updates

Ruskin automatically checks if your instrument firmware is up-to-date. Updates may be critical, routine, or customised.

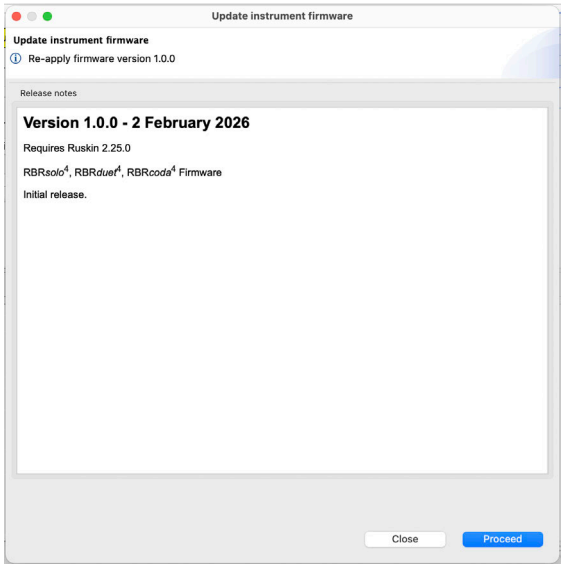
16.1 Critical firmware updates

If a newer version is available and this update is critical, the **Update firmware** button and a warning message will appear at the top of the **Deployment** tab.



Steps

1. Click **Update firmware**.
   The **Update instrument firmware** window will appear. It will contain **Release notes**, outlining the new version number, its release date, improvements, and bug fixes associated with this release, and two standard buttons at the bottom of the window: **Close** and **Proceed**.
2. Click **Proceed** to initialise the update.
   The instrument will disappear from the **Navigator** window during the upgrade. Watch the progress bar at the bottom of the window for the status.



Do not disconnect the instrument until a confirmation message is displayed. Disconnecting during the update process may render the instrument inoperable.

If the upgrade does not complete successfully, go to **Instruments** > **Update firmware...**

The **Update firmware** window will appear. Click **Proceed** again to retry.

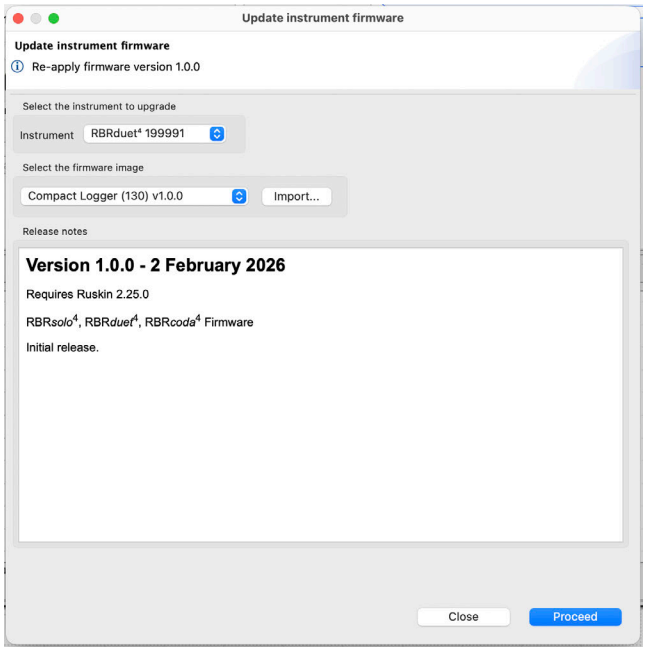
If the instrument does not reappear in the **Navigator** window after a firmware update, disconnect your instrument from the USB port and then reconnect to establish communication.

16.2 Routine firmware updates

If the latest update is not critical, Ruskin will not display any warning message. However, you can always check manually if a newer firmware warning is available.

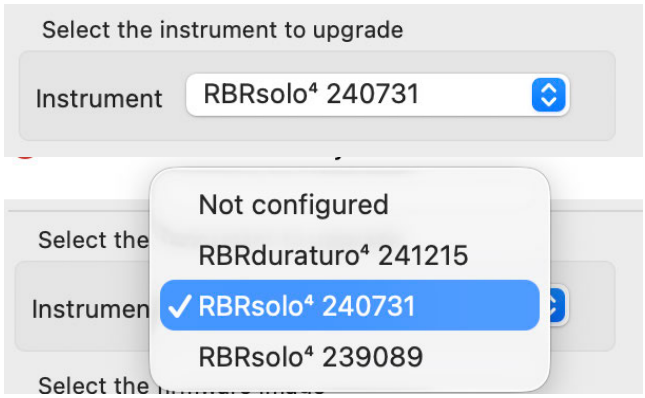
Go to **Instruments** > **Update instrument firmware.**

The **Update instrument firmware** dialog box will appear. In addition to the new version number, its release date, improvements, and bug fixes, there will be two additional sections: **Select the instrument to update** and **Select the firmware image**.



Steps

1. From the I**nstrument** dropdown, select the instrument you wish to upgrade.



2. From the firmware selection dropdown, select the latest firmware image.
3. Click **Proceed** to initialise the update.
   The instrument will disappear from the **Navigator** window during the upgrade. Watch the progress bar at the bottom of the window for the status.

Do not disconnect the instrument until a confirmation message is displayed.
Disconnecting during the update process may render the instrument inoperable.

If the upgrade does not complete successfully, click **Proceed** again to retry.

If the instrument does not reappear in the **Navigator** window after a firmware update, disconnect your instrument from the USB port and then reconnect to re-establish communication.

16.3 Manual firmware updates

In certain cases, RBR may supply a customised firmware version, which will not be on the dropdown list.

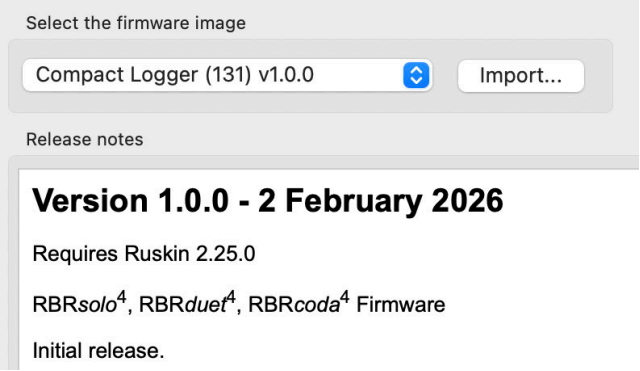
Go to the **Instruments** > **Update firmware...**

The **Update logger firmware** dialog box will appear. Follow the steps below to import the firmware image provided by RBR and update your firmware.

Steps

1. In the **Update logger firmware** dialog box, click **Import**.
2. Browse to the location of the firmware update file. The file will have the extension .rbrfw.

3. Select the file and click **Open.** The file will appear on the dropdown list.



4. Click **Proceed** to initialise the update. The instrument will disappear from the **Navigator** window during the upgrade. Watch the progress bar at the bottom of the window for the status.

Do not disconnect the instrument until a confirmation message is displayed. Disconnecting during the update process may render the instrument inoperable.

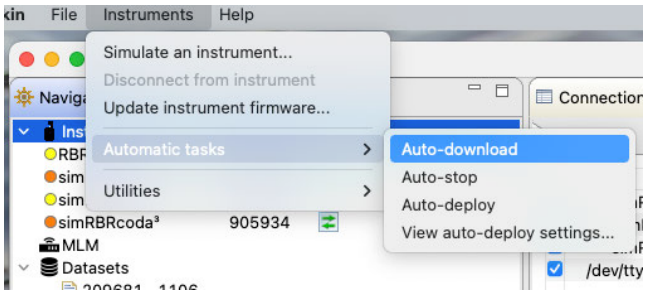
17 Automatic tasks

When working with a large number of similar instruments, Ruskin offers various automatic tasks.

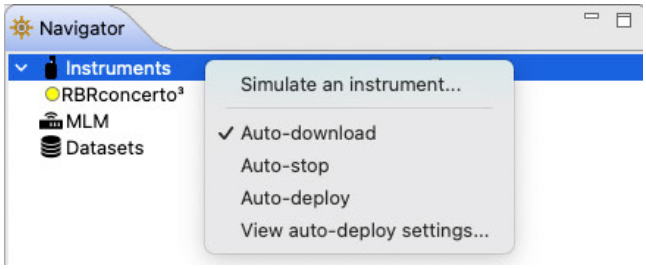
When using this feature, you will configure your schedule once and then automatically apply the settings to multiple instruments.

> ⚠ Automatic tasks do not work with wi-fi connected instruments.

Access these options from the **Instruments** menu on the top toolbar.



Alternatively, right-click **Instruments** in the **Navigator** window.



When you enable a task, it will show a checkmark next to it, and the corresponding icon will be displayed in the **Navigator** window.

Since these tasks can change the state of your instrument, their settings default to "off" each time Ruskin is run.

When an automatic task is on, Ruskin will execute it as soon as you plug an instrument into your computer.

Auto-download

When Ruskin detects an instrument, it will automatically start a download process. The downloaded dataset will be named following the standard naming convention, and saved in the default directory. Other than possibly creating unwanted files, this option is safe since it does not alter the state of the instrument.

Auto-stop

When Ruskin detects a previously enabled instrument, it will automatically stop the deployment. If auto-download is not selected, it will also display a warning about downloading the instrument data.

Use this feature when Gating is set to **Now**.

⚠ All the data on the instrument will be erased as soon as you enable a new deployment. RBR recommends enabling the **Auto-download** feature whenever you enable **Auto-stop**.

Auto-deploy

When Ruskin detects an instrument, it will stop the deployment and then reprogram your instrument with the last known configuration settings. Use this feature when you have several instruments with the same capabilities

⚠ All the data on the instrument will be erased as soon as you enable a new deployment. RBR recommends enabling the **Auto-download** feature whenever you enable **Auto-deploy**.

To use this feature, follow these steps:

1. Connect to an instrument that will act as the model.
2. Configure this instrument with the desired settings.
3. Enable **Auto-deploy** as shown above.

Now, when you connect to an instrument with same capabilities as the model instrument, Ruskin will configure it to match the the model schedule.

⚠ **Auto-deploy** implies **Auto-stop.**

Ruskin must stop your instrument to change deployment parameters, so it will stop even when there is no checkmark next to the **Auto-stop** task.

View auto-deploy settings

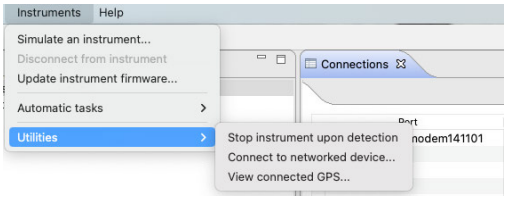
To view the currently active auto-deploy parameters, go to **Instruments > Automatic tasks > View auto-deploy settings...** .

The **Auto-deploy settings** box will open, with saved parameters outlined.

18 Utilities

The **Utilities** option is a support tool. Contact RBR before using it.

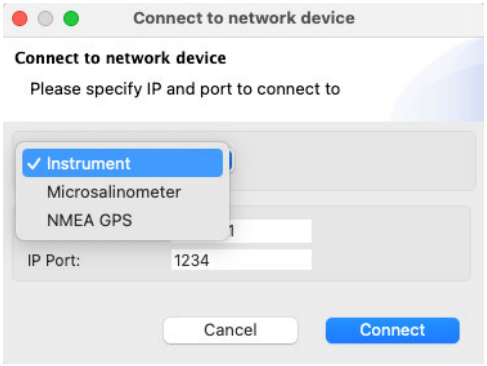
From the **Instruments** menu, click **Utilities**. A dropdown menu will open.



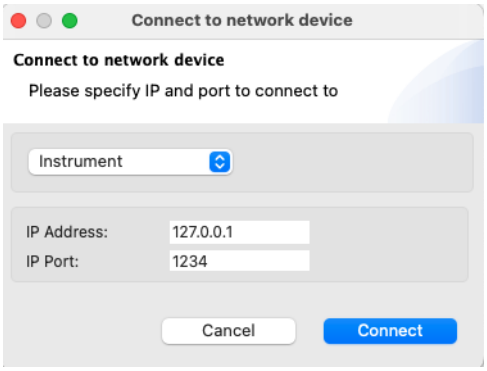
Connect to networked device...

This utility allows a device with serial output to connect to your network via Ethernet. This feature supports remote management and monitoring of your instruments from anywhere in the world.

1. Select your network device from the dropdown list.

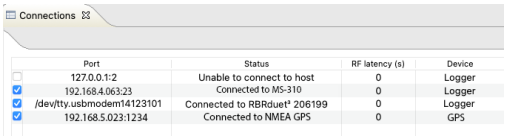


2. Specify the IP address and port.



For the microsalinometer, the port number must be **23**.

3. Click **Connect**.
   The **Connections** tab will display instruments and salinometers connected via Ethernet, alongside with the instruments physically plugged in to your computer. Their IP address and port will appear in the **Port** column. If an attempt to connect was unsuccessful, Ruskin will report an error in the **Status** column.



To view connected GPS devices, go to the next utility.

View connected GPS...

This feature allows you to track your instruments during towed deployments. Attach a NMEA GPS to your computer and connect to it as described above. Alternatively, connect to one of the boat tracking devices if it has an IP address.

Typically, only one GPS is necessary to track your deployment. Using more than one GPS may bring confusion into your data. Click **View connected GPS...** to see all listening ports. Click the **Port** button to disconnect.

19 Revision history

Revision No.	Release Date	Notes
A	19 February 2026	Initial release